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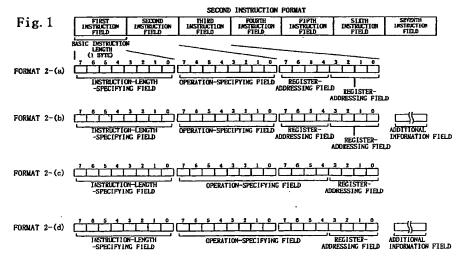
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#### (54) Data processor compatible with a plurality of instruction formats

(57) A data processor according to the present invention executes instructions described in first and second instruction formats. The first instruction format defines a register-addressing field of a predetermined size, while the second instruction format defines a register-addressing field of a size larger than that of the register-addressing field defined by the first instruction format. The data processor includes: instruction-type identifier, responsive to an instruction, for identifying the received instruction as being described in the first or second instruction format by the instruction itself; a first register file including a plurality of registers; and a second register file also including a plurality of registers, the

rumber of the registers included in the second register file being larger than that of the registers included in the first register file. If the instruction-type identifier has identified the received instruction as being described in the first instruction format, the data processor executes the instruction using data held in the first register file. On the other hand, if the instruction-type identifier has identified the received instruction as being described in the second instruction format, the data processor executes the instruction using data held in the second register file.



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#### Description

#### **BACKGROUND OF THE INVENTION**

The present invention relates to an improved data processor implemented as CPU or microprocessor, for example, and more particularly relates to a data processor adapted for use with an instruction set suitable for downsizing a program.

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[0002] As semiconductor technologies and architecture of processors have been vigorously researched and developed over the past few years, the performance of programmable data processors of various types, termed "CPU's", have also been tremendously improved. Depending on their specific applications, CPU's may be roughly classified into the following two types: general-purpose microprocessors; and built-in microcontrollers for use in numerous kinds of control units and consumer electronics appliances. As for CPU's of the first type, that is, general-purpose micro- :203 processors, improvement of performance is a top priority. Therefore, for the sake of improving the performance of general-purpose microprocessors, a wide variety of techniques have heretofore been employed. In contrast, 1998 with regards to built-in microcontrollers, it is true that 25% in Figure 22(b), only 3 bits are available for each regisimprovement of performance is one of most significant. objects to be achieved. What is more important is, however, striking an appropriate balance among perform-10-10-1 ance improvement, cost effectiveness and reduction in power consumption. Among other things, the cost effec- 3004 tiveness plays a key role in meeting a high demand in Confe consumer electronics applications.

[0003] There are two tips for realizing a CPU at a state. lower cost: reducing the size of a CPU itself (i.e., reducing the area of a CPU core); and shrinking the size of a program (or the size of a ROM). In recent years, as the performance of a CPU has been improved, the number [35] of functions implementable by a single CPU has increased and the size of an application program has further increased correspondingly. Under the circumstances such as these, the size of a ROM for storing such a large-sized program dominates over the area of a CPU core. Accordingly, the cost effectiveness of a CPU is greatly dependent on how small the size of a program, applicable to the CPU, can be.

The prior art, developed to solve this task, will be described. In accordance with this technique, the architecture of an instruction set for a general-purpose microprocessor is extended to reduce the size of a program.

[0005]Figure 22 illustrates examples of MIPS architecture instruction format for a data processor in the pertinent prior art. Specifically, Figure 22(a) illustrates a MIPS-II/III instruction format used for executing a register-to-register instruction where the length of a basic instruction word (hereinafter, simply referred to as a "basic instruction length") is fixed at 32 bits. In contrast, Figure 22(b) illustrates MIPS16 instruction formats where the basic instruction length is fixed at 16 bits.

In accordance with the MIPS architecture, 32 registers are provided. Thus, an instruction set in the MIPS-II/III format includes a plurality of registeraddressing fields each composed of 5 bits. Also, since three operands are specified according to the MIPS-II/III format, this instruction set includes three registeraddressing fields rs, rt and rd. The operation and functions of the instruction are defined using a 6-bit OP field. a 5-bit shamt field and a 6-bit func field. Accordingly, this instruction set has a fixed length of 32 bits in total.

[0007] In contrast, two types of instruction formats are definable for a register-to-register instruction included in an instruction set according to the MIPS16 format. In: one of the two types of instruction formats, two 3-bit register-addressing fields rx and ry are provided to specify two operands and the operation and function of the instruction are defined using a 5-bit OP field and a 5-bit func field. In the other instruction format, three 3-bit register-addressing fields rx, ry and rz are provided to specify three operands and the operation and function: 2017 of the instruction are defined using a 5-bit OP field and a 2-bit F-field 2 1. 1 . 12 74 4 4 2 4 4 3

[0008] In accordance with the MIPS16 format shown 1/2 ter-addressing field. Accordingly, not all the 32 registers  $|\epsilon| \lesssim \epsilon$ included in the original MIPS-II/III format, but some of these registers can be accessed: William 2018 100 and a second

**[00091** Any instruction in the MIPS16 instruction format can be replaced with an associated instruction in the MIPS-II/III instruction format. Such replacement of an instruction in the MIPS16 instruction format with a counterpart in the MIPS-II/III instruction format is called an "extension" of an instruction. 175 1 4 155 A

[0010] Figure 23 is a block diagram illustrating a main part of a data processor for executing instructions in the MIPS16 and MIPS-II/III formats. Hereinafter, the operation of this data processor will be described.

[0011] An instruction fetch section 300 is a block for fetching an instruction. Specifically, the instruction fetch section 300 fetches an instruction set in the MIPS16 instruction format with a fixed length of 16 bits or in the MIPS-II/III instruction format with a fixed length of 32 bits, and then outputs the fetched instruction set to an instruction extender 310. The type of the instruction set. i.e., whether the instruction set is in the MIPS16 or MIPS-II/III instruction format, is always specified by a mode setting signal.

[0012] The instruction extender 310 is also controlled by the mode setting signal. If the input instruction set is in the MIPS16 instruction format, then the instruction extender 310 extends the instruction set in the MIPS16 instruction format into that in the MIPS-II/III instruction format. Alternatively, if the input instruction set is in the MIPS-II/III instruction format, then the instruction extender 310 outputs the instruction set as it is without performing the extension. It is controlled by the mode setting signal whether or not the extension should be

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performed. Accordingly, the instruction extender 310 cannot determine the necessity from the instructions themselves. Since the mode setting signal is a programmable signal, the mode of operations can be switched at a desired time.

[0013] An instruction decoder 320 is a block for decoding the instruction in the MIPS-II/III instruction format and thereby producing a control signal. The operation of the data processor is controlled by the control signal produced by the instruction decoder 320.

The data processor having such a configuration can execute both a program described in the MIPS16 instruction format with a basic instruction length of 16 bits and a program described in the MIPS-IVIII instruction format with a basic instruction length of .. 15 described in these formats, are identifiable by the 32 bits. Accordingly, if the code size should be priori- an instructions themselves. Accordingly, an application tized, then programming is preferably carried out using. a requiring a large number of registers, like signal the MIPS16 instruction format with a fixed length of 16 ( ), re-processing; can be performed at a higher speed without bits. On the other hand, if the performance should be the increasing the code size. respected first to access as large a number of register 203 [0020] . Specifically, a data processor according to the files as possible, then programming may be conducted: way present invention executes an instruction described in a using the MIPS-II/III instruction format. Thus, a program was a first instruction format and an instruction described in a can be developed flexibly with a good balance struck seal, second instruction format. The first instruction format between performance and code size. Nevertheless, it we do defines a register-addressing field of a predetermined depends sometimes on the specifications of a particular, 1125% size, while the second instruction format defines a regsystem and sometimes on the size of a program which ... ister-addressing field of a size larger than the size of the type of instruction formats should be used. For example, again register-addressing field defined by the first instruction a certain type of format is used only when the size of a legg format. The data processor includes, means, responprogram reaches that of a task. . . ....

an application, (like signal processing) as requiring a: 100 format by the instruction itself; a first register file includlarge number of registers, the number of available registers should preferably be increased by adding, some to the including a plurality of registers, the number of the regregisters to preexistent ones such that the application can be performed at an even higher speed. In such a ( ,350) than the number of the registers included in the first regcase, an instruction format, allowing the user to specify one ister file. If the identifying means has identified the a larger number of registers than a conventional instruction, a received instruction as, being described in the first tion format, may be produced and used instead of the property instruction format, the data processor executes the conventional instruction format. However, the size of  $\mathbf{a}_{i,j}$ ,  $\mathbf{a}_{i,j}$  instruction using data held in the first register file. On the resultant program considerably increases by the use of 49% other hand, if the identifying means has identified the such an alternate instruction formation for the

[0016]. Thus, the prior art may be modified in the following manner. A new instruction format, allowing the an instruction using data held in the second register file. user to specify a larger number of registers, may be provided in addition to the conventional instruction format. 45: And the newly provided instruction format and the conventional instruction format may be selectively employed in response to the mode setting signal of the prior art.

[0017] Nevertheless, if the mode setting signal of the prior art is used, then the code size still increases disadvantageously. That is to say, a switching instruction should be given to generate the mode setting signal in switching the instruction formats. Accordingly, if a plurality of instructions, described in these formats, are included within a single instruction set, then the switching instructions should also be given numerous number of times, thus adversely increasing the code size.

#### SUMMARY OF THE INVENTION

An object of this invention is providing a data processor allowing for the use of additional registers to execute instructions in several types of instruction formats included within a single instruction set and to switch these formats without the mode setting signal while effectively reducing the code size.

[0019] To achieve this object, according to the present invention, a first instruction format, allowing the user to specify a number of registers, and a second instruction format, allowing the user to specify a larger number of registers than that of the registers specified in the first instruction format, are used. The types of instructions,

way sive to an instruction, for identifying the received instruc-In order for a microprocessor to perform such 200 tion as being described in the first or second instruction isters included in the second register file being larger  $r = r \cdot r \cdot r \cdot r$  received instruction as being described in the second instruction format, the data processor executes the

In one embodiment of the present invention,... the first instruction format defines a number of instruction fields and the second instruction format defines; another number of instruction fields. And the identifying means identifies the received instruction as being described in the first or second instruction format by the contents of at least one of the instruction fields of the instruction that is defined by at least one predetermined ordinal number.

In another embodiment of the present inven-100221 tion, the number of the instruction fields defined by the second instruction format is larger than the number of the instruction fields defined by the first instruction for-

[0023]: In still another embodiment, the predetermined

ordinal number of the instruction field used by the identifying means for format identification is first.

[0024] In still another embodiment, the second register file includes all of the registers included in the first register file.

[0025] In still another embodiment, the data processor further executes an instruction described in a third instruction format. The third instruction format specifies a plurality of operations and defines a register-addressing field of a size larger than that of the registeraddressing field defined by the first instruction format. The register-addressing field defined by the third instruction format is used to specify one of the registers included in the second register file. Responsive to an instruction, the identifying means identifies the received. instruction as being described in the third instruction format by the instruction itself.

Another data processor according to the [0026] present invention also: executes an instruction described in a first instruction format and an instruction 20 described in a second instruction format. The data processor includes: a register file including a predetermined number of registers, an address described in the first instruction format for specifying one of the registers to being different from an address described in the second 25 instruction format for specifying the same register; an address converter for receiving the rinstruction described in the first instruction format and converting an address described in the first instruction format, ters, into an address described in the second instruction 143 miles format; and means, responsive to an instruction, for by the output of the identifying means.

tion format is provided for use in defining an arrangement of an instruction to be executed by a data by can be processed faster. processor. The instruction format is implemented as 40 [0031] first and second instruction formats. The first instruction format defines a number of instruction fields and the second instruction format defines another number of instruction fields, the number of the instruction fields defined by the second instruction format being larger than the number of the instruction fields defined by the first instruction format. At least one of the instruction fields that are defined by the first and second instruction formats is used to identify the type of the instruction to be executed as being described in the first or second instruction format. The first instruction format defines a register-addressing field of a predetermined size, while the second instruction format defines a registeraddressing field of a size larger than the size of the register-addressing field defined by the first instruction format.

[0028] In one embodiment of the present invention, the instruction format is implemented as a third instruc-

tion format. The third instruction format defines still another number of instruction fields, the number of the instruction fields defined by the third instruction formatbeing larger than the number of the instruction fields defined by the first instruction format. The third instruction format defines a register-addressing field of a size larger than the size of the register-addressing field defined by the first instruction format. At least one of the instruction fields that are defined by the third instruction format is used to identify the type of the instruction to be executed as being described in the third instruction format. And the third instruction format describes a plurality of operations to be executed.

[0029] According to the present invention, the instruction itself is input to the identifying means, which identifies the instruction format thereof. In this case, the identifying means identifies the instruction format of the received instruction by the instruction itself, e.g., the contents of the first instruction field of the instruction. Accordingly, unlike the prior art, there is no need to use: any special instruction to generate a mode setting signal or the like and the code size does not increase invain. Accordingly, it is possible to effectively reduce the . size of a program while allowing the user to execute a plurality of instructions described in several types of instruction formats included within a single instruction Set. Parkers with a strong out of a second of the

[0030] Last In radditional in executing an instruction described in the first instruction format, a register to be specified by the instruction to access one of the registables accessed is specified from only a smaller number of registers included in the first register file. On the other hand, in executing an instruction described in the secidentifying the received instruction as being described in the ond instruction format, a register to be accessed can be a the first or second instruction format by the instruction appearance specified from a larger number of registers included in itself. The output of the address converter is controlled 35% the second register file. In this manner, arithmetic operations using these many registers can be described [0027] According to the present invention, an instruction within a single instruction. Accordingly, the memory 5 does not have to be accessed so frequently and data

> As can be understood, the present invention. makes it possible to increase the number of usable registers and the speed of data processing while effectively reducing the size of a program.

> [0032] 9 Moreover, in accordance with the present invention, a plurality of operations can be specified within a single instruction described in the third instruction format. Accordingly, these operations, defined within a single instruction, can be performed in parallel. thus increasing the speed of data processing even more.

[0033]Furthermore, even if a bit assignment on the instruction code used to specify a register in the first instruction format is different from that used to specify the same register in the second instruction format, these bit assignments can be equalized through the address conversion by the address converter. Accordingly, complete compatibility can be maintained between a plurality of instruction formats, i.e., an.

instruction set described in one of the instruction formats can be executed without rewriting the instruction set into another instruction format.

#### **BRIEF DESCRIPTION OF THE DRAWINGS**

#### [0034]

Figure 1 is a diagram illustrating a second instruction format for a data processor according to an exemplary embodiment of the present invention. Figure 2 illustrates part of a list of instructions in the

second instruction format to be executed by the data processor.

Figure 3 is a diagram illustrating a third instruction format for the data processor according to the embodiment of the present invention.

Figure 4 illustrates part of a list of instructions in the of third instruction format to be executed by the data - 1 4 374 27 15 3,07 \$ 320 processor.

Figure 5 is a block diagram illustrating an overalling take arrangement of the data processor. (1987) 1990 (1988) 100 (1998) Figure 6 is a block diagram illustrating an arrangement registers in a register file of the data processo with 

Figure 7 is a table of correspondence illustrating as an respective relationships among names, numbers and types of registers in the register file and associated and ated bit assignments where the data processor exercises? cutes instructions in the first instruction format. (1996) DESCRIPTION OF THE PREFERRED EMBODI-Figure 8 is a table of correspondence illustrating Land MENTS respective relationships among names, numbers in a continuous in C.

with the first instruction format.

Figure 11 illustrates a second example where the ture of this embodiment. program shown in Figure 9 is compiled in accordance with the first instruction format. 👙

Figure 12 illustrates a third example where the program shown in Figure 9 is compiled in accordance 45 with the first instruction format.

Figure 13 illustrates an example where the program shown in Figure 9 is compiled in accordance with the second instruction format.

Figure 14 illustrates an FIR filter processing program described without using instructions in the third instruction format according to the embodiment of the present invention.

Figure 15 illustrates a program obtained by rewriting the FIR filter processing program shown in Figure 14 in accordance with the third instruction format according to the embodiment of the present invention.

Figure 16 is a diagram illustrating a first instruction format (1) for the data processor according to the embodiment of the present invention.

Figure 17 illustrates part of a list of instructions in the first instruction format (1) to be executed by the data processor.

Figure 18 is a diagram illustrating a first instruction format (2) for the data processor.

Figure 19 illustrates part of a list of instructions in the first instruction format (2) to be executed by the data processor.

Figure 20 is a block diagram illustrating an arrangement of register in a first register file of the data processor.

Figure 21 is a table of correspondence illustrating respective relationships among names, numbers and types of registers in the register-file and associated bit assignments where the data processor executes instructions in the first instruction format.

Figures 22(a) and 22(b) are diagrams illustrating exemplary instruction formats for a prior art data processor. : THE ROYAL PROPERTY WITH THE PROPERTY OF THE PARTY.

Figure 23 is a block diagram illustrating an arrangement of a main part of the prior art data processor around an instruction decoders as as an

Figure 24 is a diagram illustrating specific examples of first, second and third instruction formats used in the embodiment of the present invention.

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and types of registers in the register file and associated bit assignments where the data processor exercises present invention will be described with reference to the cutes instructions in the second instruction format: 35 3 accompanying drawings. Before the arrangement of the Figure 9 illustrates an example of a program written and data processor of the present invention is described, three types of instruction formats used in the following Figure 10 illustrates a first example where the program embodiments will be described. gram shown in Figure 9 is compiled in accordance. [0036] Figures 16 through 19 illustrate an outline of a first instruction format in accordance with the architec-1 19

[0037] In the first instruction format, a variable-length instruction with a minimum instruction length of 1 byte is described. A 2-bit field is used as a register-addressing field. Accordingly, four registers can be specified with one register-addressing field. In this architecture, four . address registers and four data registers are defined: By separately using the address registers or the data registers responsive to a specific instruction, eight registers can be used in total in executing an instruction. [0038] . Figure 16 illustrates a bit assignment for the

first instruction format (1) in which a first instruction field composed of 1 byte, equal to the minimum instruction length, consists of an operation-specifying field and an arbitrary number of register-addressing fields. Specific examples of this format will be described below.

[0039] In an exemplary first instruction format (1)-(a), the first instruction field includes two 2-bit registeraddressing fields and is composed of 1 byte, which is the minimum instruction length. And two operands can be specified in accordance with this format.

[0040] In another exemplary first instruction format (1)-(b), the first instruction field includes two 2-bit register-addressing fields, and an additional information field is further provided. Thus, the instruction length in accordance with this format is 2 bytes or more in total. [0041] In still another exemplary first instruction format (1)-(c), the first instruction field includes one 2-bit register-addressing field and is composed of 1 byte, which is the minimum instruction length. And one operand can be specified in accordance with this format.

[0042] In yet another exemplary first instruction format (1)-(d), the first instruction field includes one 2-bit register-addressing field, and an additional information field is further provided. Thus, the instruction length in accordance with this format is 2 bytes or more in total.

[0043] In yet another exemplary first instruction format (1)-(e), the first instruction field includes no register-addressing fields and is composed of 1 byte, which is the minimum instruction length. Accordingly, in accordance with this format, no operands can be specified using addresses:

[0044] In yet another exemplary first instruction format 125 (1)-(f), the first instruction field includes no register-2014 addressing fields but an additional information field is 16.2 further provided. Thus, the instruction length in accordance with this format is 2 bytes or more in total.

[0045] Figure 17 illustrates part of a list of specific so instructions for respective types of bit assignment shown in Figure 16. In Figure 17, instruction mnemonics is are shown on the left and the operations performed to execute these instructions are shown on the right.

[0046] Figure 18 illustrates a bit assignment for a first [138] instruction format (2) in which a first instruction field [156] composed of 1 byte, i.e., the minimum instruction [157] length, consists of an instruction-length-specifying field [158] and a second instruction field consists of an operation-specifying field and an arbitrary number of register—[157] addressing fields. Specific examples of this format will [157] be described in detail below.

[0047] In an exemplary first instruction format (2)-(a), the second instruction field includes two 2-bit register-addressing fields and the first and second instruction fields are composed of 2 bytes. And two operands can be specified in accordance with this format.

[0048] In another exemplary first instruction format (2)-(b), the second instruction field includes two 2-bit register-addressing fields, and an additional information field is further provided. Thus, the instruction length in accordance with this format is 3 bytes or more in total.

accordance with this format is 3 bytes or more in total. [0049] In still another exemplary first instruction format (2)-(c), the second instruction field includes one 2-bit register-addressing field and the first and second instruction fields are composed of 2 bytes. And one operand can be specified in accordance with this format.

[0050]. In yet another exemplary first instruction format (2)-(d), the second instruction field includes one 2-bit register-addressing field, and an additional information field is further provided. Thus, the instruction length in accordance with this format is 3 bytes or more in total.

[0051] In yet another exemplary first instruction format (2)-(e), the second instruction field includes no register-addressing fields and the first and second instruction fields are composed of 2 bytes. Accordingly, in accordance with this format, no operands can be specified using addresses.

[0052] In yet another exemplary first instruction format (2)-(f), the second instruction field includes no register-addressing fields but an additional information field is further provided. Thus, the instruction length in accordance with this format is 3 bytes or more in total.

[0053] Figure 19 illustrates part of a list of specific instructions for respective types of bit assignment shown in Figure 18. In Figure 19, instruction mnemonics are shown on the left and the operations performed to execute these instructions are shown on the right.

[0054] Accordingly, in accordance with the first

instruction format shown in Figures 16 through 19, the instruction length of the first instruction field is used as a basic instruction length to specify a variable-length instruction. And an instruction can be described in this format to have a length N times as large as the basic instruction length and equal to on less than the maximum instruction length, which is M times as large as the basic instruction length (where N and M are both positive integers and  $1 \le N \le M$ ). Since the minimum instruction length is 1 byte, this instruction format is suitable for downsizing a program.

[0055] Figure 20 illustrates a first register file 220 included in the data processor of the present invention. The first register file 220 includes: four address registers A0 through A3; four data registers D0 through D3; a stack pointer (SP) 223; a processor status word (PSW) 224 for holding internal status information and control information; and a program counter (PC) 225. The first register file 220 further includes two read ports and one write port, thereby enabling reading from two registers (or reading from one register twice) and writing into one register simultaneously.

[0056] Figure 21 is a table illustrating accessing the address and data registers A0 through A3 and D0 through D3 included in the first register file 220 in greater detail. Specifically, this is a table of correspondence among name of a register specified by an instruction, bit assignment on an instruction code specified in a register-addressing field, and number and name of a physical register to be accessed.

[0057] In the first instruction format, the set of instruction addressing fields specified by respective instructions to access the four address registers A0 through A3 is the same as the set of instruction addressing fields specified by respective instructions to access the four data registers D0 through D3 as shown in Figure

21. That is to say, the same 2-bit instruction addressing field is used to address a desired register, and it is determined by the operation of the instruction itself whether an address register or a data register should be accessed.

[0058] Next, respective bit assignments for second and third instruction formats, which are added as respective extensions to the first instruction format shown in Figures 16 and 18, i.e., the basic instruction format of this architecture, will be described with reference to Figures 1 and 3.

[0059] In each of the bit assignments shown in Figure 1 for the second instruction format, a first instruction field, composed of 1 byte, which is the minimum instruction length, consists of an instruction-length-specifying field. And second and third instruction fields consist of an operation-specifying field and an arbitrary number of register-addressing fields: In accordance with the second instruction format, each register-addressing field is composed of 4 bits. Specific examples of this format will second by described in detail below.

[0060] In an exemplary second instruction format (a) (4.65) the third instruction field includes two 4-bit register-yearaddressing fields and the first through third instruction: and fields are composed of 3 bytes in total. And two oper-: 926 ands can be specified in accordance with this format. HOLD [0061] In another exemplary second instruction format [19,3] (b), the third instruction field includes two 4-bit-register-page addressing fields, and an additional information field is the further provided. Thus, the instruction length in accordance with this format is 4 bytes or more in total. #4# % 5 996 In still another exemplary second instruction and format (c), the third instruction field includes one 4-bit register-addressing field and the first through third each instruction fields are composed of 3 bytes in total. And 35 one operand can be specified in accordance with this format. • Committee of the second of the second contractions

[0063] In yet another exemplary second instruction format (d), the third instruction field includes one 4-bit register-addressing field, and an additional information 40 field is further provided. Thus, the instruction length in accordance with this format is 4 bytes or more in total.

[0064] Thus, in accordance with the second instruction format the instruction length of first instruction field.

tion format, the instruction length of first instruction field is also used as a basic instruction length. And an instruction can be described in this format to have a variable length N times as large as the basic instruction length and equal to or less than the maximum instruction length, which is M times as large as the basic instruction length (where N and M are both positive integers and  $1 \le N \le M$ ).

[0065] Figure 2 illustrates part of a list of specific instructions for respective types of bit assignment shown in Figure 1. In Figure 2, instruction mnemonics are shown on the left and the operations performed to execute these instructions are shown on the right. The mnemonic Rm, Rn or Ri indicates the address of a specified register. In this case, any of sixteen general-

purpose registers, namely, four address registers A0 through A3, four data registers D0 through D3 and eight extended registers E0 through E7, may be specified. Addressing of registers, as well as the configuration thereof, will be described in greater detail later.

[0066] In each of the bit assignments shown in Figure 3 for the third instruction format, a first instruction field, composed of 1 byte, which is the minimum instruction length, consists of an instruction-length-specifying field. A second instruction field consists of first and second operation-specifying fields, each composed of 4 bits. Each of third and fourth instruction fields consists of: a pair of 4-bit register-addressing fields: a pair of 4-bit operation-specifying fields; or a combination of one 4-bit register-addressing field and one 4-bit operation-specifying field. In accordance with the third instruction fermat, each register-addressing field is composed of four bits. In the following description, respective operations specified by the first and second operation-specifying fields, which are located in the second instruction field of the instruction described in this third instruction for mat, will be called "units". artital facilities

[0067] Each unit is one of the instructions described in this third instruction format and corresponds to one of various instructions described in the second instruction format and used particularly frequently. In accordance with this third instruction format, the length of each operation-specifying field is shortened from eight bits in the second instruction format into four bits. Accordingly, two operations to be executed in parallel to each other can be described within a pair of operation-specifying fields. Thus, in accordance with this third instruction format, although the number of operations that can be described is limited, the code size thereof is smaller as compared with describing operations in the second instruction format.

[0068] In an exemplary third instruction format (a) shown in Figure 3, the total instruction length is four bytes. The second instruction field consists of first and second operation-specifying fields, each composed of four bits. Each of the third and fourth instruction fields includes a pair of 4-bit register-addressing fields. Thus, four operands can be specified in accordance with this instruction format.

[0069] In another exemplary third instruction format (b) shown in Figure 3, the total instruction length is also four bytes. The second instruction field also consists of first and second operation-specifying fields, each composed of four bits. The third instruction field consists of one 4-bit register-addressing field and a first operation-specifying field composed of four bits. And the fourth instruction field consists of a pair of 4-bit register-addressing fields. Thus, three operands can be specified in accordance with this instruction format.

[0070] In still another exemplary third instruction format (c) shown in Figure 3, the total instruction length is also four bytes. The second instruction field also consists of first and second operation-specifying fields,

each composed of four bits. The third instruction field consists of a pair of 4-bit register-addressing fields. And the fourth instruction field consists of one 4-bit registeraddressing field and a second operation-specifying field composed of four bits. Thus, three operands can be specified in accordance with this instruction format.

In yet another exemplary third instruction format (d) shown in Figure 3, the total instruction length is also four bytes. The second instruction field also consists of first and second operation-specifying fields, each composed of four bits. The third instruction field consists of one 4-bit register-addressing field and a first operation-specifying field composed of four bits. And the fourth instruction field consists of one 4-bit registeraddressing field and a second operation-specifying field 15 composed of four bits. Thus, two operands can be specified in accordance with this instruction format.

mat (e) shown in Figure 3; the total instruction length is work ter 103. also four bytes. The second instruction field also con-: 20 / [0080] - Specifically, the instruction decoder 110 sists of a pair of 4-bit register-addressing fields. And the colours a register address converter 113; an operation decoders a fourth instruction field consists of first and second oper-till and first and second register address selectors and second register address selectors ation-specifying fields each composed of four bits a 25% 117 and 1187% and 1187% and a second of the Thus, two operands can be specified in accordance with. 100 [0081] The instruction-type identifier 111 decodes the

instruction format, the first instruction field specifies a

Figure 4 illustrates part of a list of specific 40 instructions for respective types of bit assignment shown in Figure 3. In Figure 4, instruction mnemonics are shown on the left and the operations performed to execute these instructions are shown on the right. The mnemonic Rm1, Rn1, Rm2 or Rn2 indicates the 45 address of a specified register. In this case, any of sixteen general-purpose registers, namely, four address registers A0 through A3, four data registers D0 through D3 and eight extended registers E0 through E7, may be specified. Also, imm4 indicates a 4-bit immediate value. Furthermore, Rm1 and Rn1 are used to execute the first unit specified by the first operation-specifying field in the second instruction field, while Rm2 and Rn2 are used to execute the second unit specified by the second operation-specifying field in the second instruction field. For details, see the following description of operation. [0076] Figure 5 is a block diagram illustrating an overall arrangement of a data processor according to an

exemplary embodiment of the present invention.

[0077] The data processor has a five-stage pipelining structure consisting of: an instruction fetch (IF) stage; a decode and register read (DEC) stage; an execution (EX) stage; a memory access (MEM) stage; and a register write back (WB) stage.

[0078] As shown in Figure 5, the IF stage includes: an instruction memory 101; an instruction fetch section 102; and an instruction register 103. The instruction memory 101 stores a program. The instruction fetch section 102 reads out a variable-length instruction, described in the first, second or third format, from the instruction memory 101. And the instruction register 103 stores the variable-length instruction that has been read out via the instruction fetch section 102.

[0079]. The DEC stage includes an instruction decoder 110 for receiving and decoding the variable-length [0072]. In yet another exemplary third instruction for-10.51

sists of first and second operation-specifying fields each [10] includes: an instruction-type identifier 111; first, second [10] composed of four bits. The third instruction field con-

this instruction formations as a construction of a particle of the instruction region of the instruction region of [0073] > In this third instruction format/ each of first and . 9 19 ister 103 to identify the type of the instruction format, 1/2 second units, specified by the first and second operations i.e., which of the first, second and third instruction fortion-specifying fields in the second instruction field; 30% mats. If the type of the variable-length instruction stored is respectively, is an instruction described in the second ( 463) in the instruction register 103 is identified as the first instruction format (a) shown in Figure 2 or an instruction and instruction format, then the first register address extracdescribed in the second instruction format (d). In the late 1.30% tor 112 extracts a 2-bit register-addressing field. The ter case, the bit width of an immediate value is reduced a 18 register address converter 113 converts the value of the 6 to see that the second of th [0074] Accordingly, in accordance with the third of diaddress extractor 112, into a 4-bit register number in the e register file. If the type of the variable-length instruction variable-length instruction of 4 bytes, consisting of first stored in the instruction register 103 is identified as the second instruction format, then the second register address extractor 114 extracts a 4-bit register-addressing field. And if the type of the variable-length instruction (2013) stored in the instruction register 103 is identified as the third instruction format, then the third register address extractor 115 extracts a 4-bit register-addressing field. Thereafter, the third register address extractor 115 supplies respective register addresses for the first and second units to the first and second register address selectors 117 and 118, respectively.

The operation decoder 116 receives and decodes the variable-length instruction stored in the instruction register 103 and produces a control signal to be supplied to the EX stage. Based on the results of identification performed by the instruction-type identifier 111, the first register address selector 117 selectively supplies the output of the register address converter 113, the second register address extractor 114 or the third register address extractor 115 to a second register file 120. The second register address selector 118

selectively supplies either the output of the second register address extractor 114 or the output of the third register address extractor 115 to the second register file 120. In this embodiment, the register address converter 113 always converts the extracted register address irrespective of the type of the instruction format. However, if the instruction-type identifier 111 can identify the type of instruction quickly, the address conversion may be naturally performed only on an instruction that has been identified as being described in the first instruction format.

[0083] The second register file 120 includes the first register file 220 shown in Figure 20 and is additionally provided with eight extended registers E0 through E7. Accordingly, the second register file 120 includes six- · .15 teen general-purpose registers in total: A0:through:A3; (10.16) field is composed of 4 bits; which is used as a physical **D0** through **D3**; and **E0** through **E7**. If the instruction in the register number as it is: question is in the first or second instruction formal, the wife. [0090]ister address selector 1.17 of the instruction idecoder: [20], described with reference to Figures 5 through 8. are used in common by these register files 120 and 220% (30%) identified at [0084] The EX stage includes: E0, E1, E2 and E3 reg- tan in [0092] ters 151 and 152, which are pipeline registers for storing the output of the data memory 143.

[0087] Figure 6 illustrates the second register file 120 extracted from Figure 5. And Figures 7 and 8 illustrate in greater detail accessing general-purpose registers included in this register file 120.

[0088] Figure 7 is a table of correspondence among name of a register specified during the execution of an instruction defined in the first instruction format, bit assignment on an instruction code specified in a register-addressing field, and number and name of a physical register to be accessed. In accordance with the first instruction format, each register-addressing field is

composed of only 2 bits. However, in this case, there are sixteen general-purpose registers, each of which should be accessed using a 4-bit address. Accordingly, address conversion should be performed. For example, in accessing an address register A0 and a data register D1, "1000" and "1101" should be produced as respective physical register numbers and then output to a file 121 of general-purpose registers.

Figure 8 is a table of correspondence among name of a register specified during the execution of an instruction defined in the second instruction format, bit assignment on an instruction code specified in a register-addressing field, and number and name of a physical register to be accessed. In accordance with the second instruction format, each register-addressing 化化铁铁 医自动

The operation of the data processor of the addresses of these registers are input from the first regard present invention having such a configuration will be 110. Alternatively, if the instruction in question is in:the Color [0091] : An instruction is given to the instruction-type third instruction format, the addresses of these registers to add identifier: 1.11 shown in Figure 5. Incresponse thereto, are input from the second register address selector 118.5 million that instruction-type identifier 111 identifies the type of The second register file 120 is different from the first: A file the given instruction, i.e., which of the first, second and register file 220 shown in Figure 20 in that the eight see third instruction formats, by deceding a particular bit in extended registers E0 through E7 are additionally pro- 18/34 the first instruction field. Then, the instruction-type idenvided for the second register file 120. The other general organization 111 produces a control signal associated with each purpose registers, i.e., the four address registers A07 sets of these formats. Hereinafter, it will be described in through A3 and the four data registers D0 (hrough D3, a secretar detail how the type of the instruction format is and the growing of the confidence and

Figure 24 illustrates specific examples of isters 131, 132, 134 and 135 for storing the respective and instruction formats. As shown in Figure 24, the first outputs from the register file 120; and operation units and instruction format (1) may be implemented as S0, S1, 133 and 136. The operation unit 133 performs an arith- Section S2, S4 or S6. The instruction S0 includes only a 1-byte metic or logical operation using the contents of the E0- 35% operation code OP and has a minimum length of one and E1 registers 131 and 132, while the operation unit enable byte. In contrast, the other instructions S1, S2, S4 and 136 performs an arithmetic or logical operation using weeks \$6 additionally includes 8-, 16-, 32- or 48-bit immediate the contents of the E2 and E3 registers 134 and:135. Fig. 127. value imm, displacement d or absolute value abs, and [0085] The MEM stage includes: M0 and M1 registers are composed of 2, 3, 5 and 7 bytes, respectively. The 141 and 142; and a data memory 143. The M0 and M1 to 40 of first instruction format (2) may be implemented as D0, registers 141 and 142 are pipeline registers for storing on ord D1, D2, D4 or D5. The instruction D0 includes only a 2the outputs of the operation units 133 and:136, respectively on byte operation code, OP and has a minimum length of tively. The data memory 143 stores the data that has the two bytes. In contrast, the other instructions D1, D2, D4 been stored in the M0 and M1 registers 141 and 142. ... ... and D5 additionally includes 8-, 16-, 32- or 40-bit imme-[0086] And the WB stage includes W0 and W1-regis-. 45- diate value imm, displacement d or absolute value abs, and are composed of 3, 4, 6 and 7 bytes, respectively. The second instruction format may be implemented as T0, T1, T3 or T4. The instruction T0 includes only a 3byte operation code OP and has a minimum length of three bytes. In contrast, the other instructions T1, T3 and T4 additionally includes 8-, 24- or 32-bit immediate value imm, displacement d or absolute value abs, and are composed of 4, 6 and 7 bytes, respectively. The third instruction format is herein implemented as an instruction Q0 and is composed of only a 4-byte operation code OP. In the instruction formats shown in Figure 24, judging only from the number of operation codes OP, the number of operation fields (i.e., three) of the

instructions T0 through T4 in the second instruction format is larger than that of the instructions S0 through S6 in the first instruction format (1) (i.e., one) or that of the instructions D0 through D5 in the first instruction format (2) (i.e., two). Also, the number of instruction fields (i.e., four) of the instruction Q0 in the third instruction format is larger than that (i.e., three) of the instructions T0 through T4 in the second instruction format. The first instruction formats (1) and (2) are assigned to instructions that can be described in a relatively small number of fields and are specified frequently. On the other hand, the second instruction format is assigned to instructions that are described in a relatively large number of fields and are specified less frequently.

[0093] . In the variable-length instructions shown in Fig. .  $\it 15$ ure 24, the bit codes are assigned to respective first bytes as shown on the right column in Figure 24 depending on the respective types S0 through S6, D0 through D5, T0 through: T4 and Q0. Accordingly, by recognizing the bit codes in the first byte, the type of the received instruction can be uniquely identified as being first, second or third instruction format. In this embodiment, the type of the instruction format is identified only 98%by the bit codes in the first byte. Alternatively, the type of 1990 the instruction format may be identified according to the  $\ensuremath{\approx}28$ present invention by: the fourth bit of the second byte (i.e., the most significant bit of the lower nibble) in addition to the first byte; part of the first byte, not all of it; or part or all of a byte that is defined by a predetermined 2000 ordinal number. The production of the control of th

[0094] First, it will be exemplified how an instruction of the MOV A0, D0 in the first instruction format is executed as well as individual times of operations. This is a register-to-register transfer instruction that the contents of the address register A0 should be read out and then stored in the data register D0.

#### (a) IF stage

1 1 3 1 1

[0095] The instruction fetch section 102 reads out the ! 40 instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0096] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the first instruction format and output a control signal indicative of the type to the first register address selector 117. The first register address extractor 112 extracts a source register address "00", which is the address of the address register A0, and a destination register address "00", which is the address of the data register D0. The register address converter 113 converts the address "00" of the address register A0 and the address "00" of the data register D0 into 4-bit addresses "1000" and "1100", respectively. Responsive to the control signal supplied

from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied from the register address converter 113, to the register file 120. The operation decoder 116 decodes the instruction as a register-to-register transfer instruction from the address register A0 to the data register D0, thereby producing an associated control signal.

[0097] The contents of the address register A0, associated with the physical address "1000", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

### (c) EX stage

[0098] The data stored in the E0 register 131 is passed through the operation unit 133 and then stored in the M0 register 141.

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#### (d) MEM stage

[0099] The data stored in the M0 register:141 is passed through the data memory 143 and then stored in the W0 register 151.

## (e) WB stage of the profile of the control of the c

[0100] The data stored in the W0 register 151 is written into the data register D0 associated with the physical address "1100".

[0101] The above-described operations enable the execution of an instruction in the first instruction format. [0102] Next, it will be exemplified how an instruction MOV A0, E7 in the second instruction format is executed as well as individual times of operations. This is a register-to-registe transfer instruction that the contents of the address register A0 should be read out and then stored in the extended register E7.

#### (a) IF stage

[0103] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

# (b) DEC stage

[0104] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "1000", which is the address of the address register A0, and a destination register address "0111", which is the address of the extended register E7. Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied from the

second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction as a register-to-register transfer instruction from the address register A0 to the extended register E7, thereby producing an associated control signal.

[0105] The contents of the address register A0, associated with the physical address "1000", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

#### (c) EX stage

The data stored in the E0 register 131 is passed through the operation unit 133 and then stored 15 in the M0 register 141. 

#### (d) MEM stage

The data stored in the M0 register 141 is passed through the data memory 143 and then stored 20 • • • . . . in the W0 register 151.

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ing the entire property

#### (e) WB stage

....

[0108] The data stored in the W0 register 151 is write: 25 ten into the extended register E7 associated with the physical add: ess "0111". 

[0109] The above-described operations enable that execution of an instruction in the second instruction for-4 4 the strain of the second . ∺: a>

[0110] Next, it will be exemplified how an instruction MOV\_MOV E5, E6, E4, E7 in the third instruction format is executed as well as individual times of operations. This is a parallel register-to-register transfer instruction and that the contents of the extended register E5 should be 1.35, read out and stored in the extended register, E6, and at the last the same time, the contents of the extended register E4 (4) should be read out and stored in the extended register E7.

#### (a) IF stage

. . . . . . . . . . . . . . . . . . . [0111] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

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#### (b) DEC stage

[0112] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the third instruction format and output a control signal indicative of the type to the first register address selector 117.

[0113] Following the first transfer instruction, the third register address extractor 115 extracts a source register address "0101", which is the address of the extended register E5, and a destination register address "0110", which is the address of the extended register E6. In

addition, following the second transfer instruction, the third register address extractor 115 also extracts a source register address "0100", which is the address of the extended register E4, and a destination register address "0111", which is the address of the extended register E7.

[0114] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the first and second sets of addresses, supplied from the third register address extractor 115, to the register file 120.

The operation decoder 116 decodes the [0115] instruction as a parallel register-to-register transfer instruction VLIW from the extended register E5 to the extended register E6 and from the extended register E4 to the extended register E7, thereby producing an associated control signal.

The contents of the extended register E5, -[0116] associated with the physical address "0101", are read out as a first source operand from the register file 120 and then stored in the E0 register 131. At the same time, the contents of the extended register E4, associated with the physical address "9100", are read out as a second source operand from the register file 120 and ... then stored in the E2 register 134.

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### (c) EXistage

and the contract by the contract of The data stored in the E0 register 131 is [0117] passed through the operation unit 133 and then stored in the M0 register 141. Simultaneously, the data stored in the E2 register 134 is passed through the operation unit 136 and then stored in the M1 register 142.

#### (d) MEM stage

[0118] The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151. Concurrently, the data stored in the M1 register 142 is passed through the data memory 143 and then stored in the W1 register 152.

#### (e) WB stage

[0119] The data stored in the W0 register 151 is written into the extended register E6 associated with the physical address "0110". At the same time, the data stored in the W1 register 152 is written into the extended register E7 associated with the physical address "0111"...

The above-described operations enable the [0120] execution of an instruction in the third instruction format. As can be understood from the foregoing description, the data processor of the present invention can execute any instruction without switching modes, no matter which of the first, second and third formats the instruction is described in. Also, the data processor of the present invention can execute an instruction set,

which has been optimized for reducing the code size, with its upward compatibility completely maintained and with the number of available registers considerably increased.

[0122] Next, specific examples showing how instructions in the first instruction format are made compatible with counterparts in the second instruction format will be described.

[0123] Figure 9 illustrates a brief example of a program written in C. This is a simple instruction that the contents of a variable a should be added to the contents of a variable b and the sum should be stored as a new variable a, and that the contents of a variable c should be added to the contents of a variable d and the sum should be stored as a new variable c.

[0124] The exemplary results obtained by compiling this program into instructions in the first instruction format are shown in Figures 10, 11 and 12.

[0125] Figure 10 illustrates an instruction set where all and ters flexibly. the variables are assigned to the data registers. Specif- [20]: [0130] ically, the variables a, b, c and d are supposed to have be the instructions in the other instruction format will be to the been successfully assigned to the data registers D0, D1, D2 and D3, respectively. Such a state is feasible by cause [0131]. Figure 14 illustrates a main part of a program of a the data processor considerably deteriorates.

[0127] Figure 12 illustrates an instruction set further

set where all the variables are assigned to extended registers in accordance with the second instruction format. Specifically, the variables a, b, c and d are supposed to have been successfully assigned to the extended registers E0, E1, E2 and E3, respectively. Such a state is feasible by executing two addition instructions. Since the number of extended registers is also limited, a sufficiently large number of registers are not always available from the extended registers. However, in this case, the number of registers available is much larger than the case shown in Figure 10, the performance of the data processor is less likely to deteriorate due to frequent access to the memory. Accordingly, in order to execute an application program, requiring a large number of registers as in signal processing, in as short a time as possible, the extended registers E0

through E7 should be added and the second instruction format should be used. In such a case, the number of times the memory is accessed can be reduced and the processing performance can be improved.

[0129] In addition, even if an address specified for a certain register in the first instruction format is different from an associated address specified for the same register in the second instruction format, the first and second instruction formats can be used interchangeably in this embodiment. This is because the address specified in the first instruction format can be converted into the address specified in the second instruction format. Accordingly, even if the number of registers is increased by the addition of extended registers, the first and second instruction formats can be used with upward compatibility completely maintained. Consequently, the a present invention is particularly advantageous in that . this data processor can cope with the addition of regis-18 P. + . . 

Next, specific examples of how to execute .... :... described... িলাল দেখালোক লিলাক লাখালোক বিভাগ কৰিছে লাখালোক বিভাগ কৰিছে লাখালোক লাখালোক লাখালোক লাখালোক লাখালোক লাখালোক লাখ

executing only two addition instructions. However, since to said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an FiRifilter that processes a medium such as a soft-control of the said for an Firifilter that processes are said for an expectation of the said for a expectation of the said for an expectation of the said for a exp there are only four data registers, it is difficult to assign 225% ware-drivens modern. In Figure 214, the program is all of these variables to the same number of registers. As a local described without using instructions in the third instructions. Figure 11 illustrates an instruction set where are a tion format, and the code sizes of respective instructhe respective variables are assigned to stack regions and the tions are shown on the right of associated operands, well on a data memory. Specifically, the variables a, b, c and a configuration of transfers a half-word transfers d are supposed to have been successfully assigned to 30% instruction from a register to a memory (store) in the first (SP+#4), (SP+#8), (SP+#12) and (SP+#16), respectively instruction format: Instruction 2 represents a half-word tively. In this case, not only the two addition instructions, and swap instruction (swap), in the second instruction forbut also eight data transfer instructions between mem- 🛷 😅 mat. Instruction (3" represents a half-word transfer 😭 ory and registers, i.e., Instructions 1 through 8, should a radi instruction from a register to a memory (store) in the be executed. As a result, the processing performance of 35 second instruction format. Instruction 4 represents a the state of the dual half-word multiply-and-accumulate instruction in the second instruction format. Instruction 5 represents a including data transfer instructions, i.e., Instructions 1,9 % 4 subtraction instruction in the second instruction format. 2, 11 and 12, to save and restore the contents of the Constructions 6 and 7 each represent a transfer instructions data registers D0 and D1, used for addition. In such a 40% tion from a memory to a register (load) in the second case, only non-destructive registers can be used. (\*\* \*\* \*\* \*\* \*\* \*\* instruction format. And Instruction 8 represents a condi- 1008 [0128] In contrast, Figure 13 illustrates an instruction is a tional branch instruction in the first instruction format. [0133] "Hereinafter, specific times of operations will be State State State

> [0134] Instruction 1 MOVH D0, (#-6, A3) is a registerto-memory transfer instruction (store) in the first instruction format that a value in the data register D0 should be stored at a memory address obtained by subtracting "6" from an address stored in the address register A3.

(a) IF stage

[0135] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0136] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the first instruction for- 5 mat and output a control signal indicative of the type to the first register address selector 117. The first register address extractor 112 extracts source register addresses "00" and "11", which are the respective addresses of the data register D0 and the address register A3. The register address converter 113 converts the address "00" of the data register D0 and the address "11" of the address register A3 into 4-bit addresses "1100" and "1011", respectively.

[0137] Responsive to the control signal supplied from the instruction-type identifier 111, the first register converter 113, to the register file 120. No are also which is the address of the extended register E2.

[0138] instruction as a register-to-memory transfer instruction. At the instruction-type identifier 111, the first register (store) that a value in the data register D0 should be 100 address selector 117 outputs the addresses, supplied stored at a memory address obtained by subtracting: 61 ms 301 from the second register address extractor 114, to the from an address stored in the address register A3, 25° register file 120. The operation decoder 116 decodes thereby producing an associated control signal.

source operand from the register file 120 and then (1890) register E2; thereby producing an associated control stored in the E0 register 131. And the contents of the cost signal of the contents of the cont address register A3, associated with the physical at the [0147] register 132.

#### (c) EX stage

unit 133 subtracts "6" from the address stored in the E1 register 132 and outputs the result of subtraction to an electronic stored in the M0 register 141. address input section of the data memory 143.

#### (d) MEM stage

[0141] The data stored in the M0 register 141 is stored in the data memory 143 at an address specified by the result of subtraction performed by the operation unit 50

#### (e) WB stage

[0142] No operations are performed.

[0143] Instruction 2 SWHW E0, E2 is an instruction in the second instruction format that data, obtained by swapping the upper and lower half words of the data

stored in the extended register E0, should be stored in the extended register E2.

#### (a) IF stage

[0144] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0145] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second address selector 117, outputs the prespective 4-bit (e.g., register address extractor 114 extracts a source register addresses "1100" and "1011" of the data and address " 0000", which is the address of the extended registers D0 and A3, supplied from the register address to register E0, and a destination register address "0010".

The operation decoder: 116 decodes the AMERIC [0146] AResponsive to the control signal supplied from the instruction to find that data, obtained by swapping [0139] The contents of the data register D0; associations the upper and lower half-words of the data stored in the ated with the physical address "1100", are read out as an arm extended register E0, should be stored in the extended

The contents of the extended register E0, address "1011", are read out as another source oper- 1997 associated with the physical address "0000", are read and from the register file 120 and then stored in the E1 out as a source operand from the register file 120 and then stored in the E0 register 131......

The second of the second second second

#### (c) EX stage

35 3 35 3

2 2 4 C 2 5 5 7 5 6 7

The data stored in the E0 register 131 is ... [0148] Responsive to the control signal supplied from passed through the operation unit 133 and then stored and the operation decoder 116, the operation unit 133 perin the M0 register 141. In response to the control signal 40% forms a swapping operation on the data stored in the E0 supplied from the operation decoder 116, the operation: 2000 register 131 by swapping the upper and lower half words thereof. Then, the result of this operation is

#### (d) MEM stage

The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151.

#### (e) WB stage

[0150] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0010" specified by the second register address extractor 114.

[0151] Instruction 3 MOVH E2, (#-4, A3) is a registerto-memory transfer instruction (store) in the second instruction format that a value in the extended register E2 should be stored at a memory address obtained by subtracting "4" from an address stored in the address register A3.

#### (a) IF stage

[0152] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

## (b) DEC stage

[0153] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The first register address extractor 112 extracts a source register ... address "11", which is the address of the address regis- : 20: ter A3. The second register address extractor 114 % .... extracts another source register address "0010", which  $\alpha = 1$ is the address of the extended register E2: The register care address converter 113 converts the address #11" of the war address register A3 into a 4-bit address "101.1". 25; [0154] Responsive to the control signal supplied from [2,47] the instruction-type-lidentifier 111,4 the first registers and address selector 117 outputs the 4-bit address \$1011. of the address register A3, supplied from the register address converter 113, and the 4-bit address "0010" of 30) the extended register E2 to the register file 120.

[0155] The operation decoder 116 decodes the instruction as a register-to-memory transfer instruction of a (store) that a value in the extended register E2 should with be stored at a memory address obtained by subtracting 35 "4" from an address stored in the address register A3, thereby producing an associated control signal.

[0156] The contents of the extended register E2, associated with the physical address "0010", are read out as a source operand from the register file 120 and 40 then stored in the E0 register 131. And the contents of the address register A3, associated with the physical address "1011", are read out as another source operand from the register file 120 and then stored in the E1 register 132.

#### (c) EX stage

[0157] The data stored in the E0 register 131 is passed through the operation unit 133 and then stored in the M0 register 141. In response to the control signal supplied from the operation decoder 116, the operation unit 133 subtracts "4" from the address stored in the E1 register 132 and outputs the result of subtraction to an address input section of the data memory 143.

#### (d) MEM stage

[0158] The data stored in the M0 register 141 is stored in the data memory 143 at the address specified by the result of subtraction performed by the operation unit 133.

#### (e) WB stage

[0159] No operations are performed.
[0160] Instruction 4 DMACH E6, E1 is an instruction in the second instruction format that a product obtained by multiplying together the respective upper half words of the data stored in the extended registers E6 and E1 should be added to a product obtained by multiplying together the respective lower half words thereof and the sum should be accumulated in the extended register

#### (a) IF stage

[0161]. The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

## (b) DEC stage in the large of the contract of the angelor and the contract of the contract of

[0162] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "0110", which is the address of the extended register E6, and a destination register address "0001", which is the address of the extended register EI.

the instruction-type identifier 111, the first register address selector 177 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction to find that a product obtained by multiplying together the respective upper half words of the data stored in the extended registers E6 and E1 should be added to a product obtained by multiplying together the respective lower half words thereof and the sum should be accumulated in the extended register E1, thereby producing an associated control signal.

[0164] The contents of the extended register E6, associated with the physical address "0110", are read out as a source operand from the register file 120 and then stored in the E0 register 131. And the contents of the extended register E1, associated with the physical address "0001", are read out as another source operand from the register file 120.

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#### (c) EX stage

The operation unit 133 extracts and multiplies together the respective upper half words of the data stored in the E0 and E1 registers 131 and 132. At the 5 same time, the operation unit 133 extracts and multiplies together the respective lower half words of the data stored in the E0 and E1 registers 131 and 132. These two products are added to the data stored in the E1 register 132. And the result of addition is stored in the M0 register 141.

#### (d) MEM stage

The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151.  $h = \xi \lambda_{i}$ 36

#### (e) WB stage

[0167] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0001" specified by the second register and in address extractor 114. A Discourse of the Address of A of the right [0168] Instruction 5 SUB 1, E3 is a subtraction instruc- 25 tion in the second instruction format that "1" should be a (\*) subtracted from the value stored in the extended register E3 and then the result of subtraction should be 3103 stored in the extended register E3. The time and a matter than are in the first of and a contract to a retain a significant

(a) IF stage ্ৰত ভূমী হ'লট সংগ্ৰহ **প্ৰাল** . . CONTRACTOR RESIDENCE

[0169] The instruction fetch section 102 reads out the pages instruction from the instruction memory 101 and then areas stores the instruction in the instruction register 103m2 (1988)

#### (b) DEC stage

[0170] The instruction-type identifier 111 decodes the at the instruction stored in the instruction register 103 to iden- 340 to tify the type of this instruction as the second instruction as the format and output a control signal indicative of the type - - - to the first register address selector 117. The second, the register address extractor 114 extracts a source register register address extractor 114 extracts a source register address "0011", which is the address of the extended vi45. register E3, and a destination register address "0011", which is also the address of the extended register E3. [0171] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction to find that "1" should be subtracted from the value stored in the extended register E3, thereby producing an associated control signal.

associated with the physical address "0011", are read out as a source operand from the register file 120 and

The contents of the extended register E3,

then stored in the E0 register 131.

#### (c) EX stage

[0173] The operation unit 133 reads out the data stored in the E0 register 131 and subtracts "1" therefrom. And the result of subtraction is stored in the MO register 141.

#### (d) MEM stage

[0174] The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151.

#### (e) WB.stage

3 July 18 2 [0175] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0011" specified by the second register address extractor 114. A 10 as a second second

[0176] Instruction 6 MOV (#4, E4+), E6 is a post-increment memory-to-register transfer instruction in the second instruction format that data should be read out from the memory address of the extended register E4 and then stored in the extended register E6 and the value of the extended register E4 should be increased by "4" after the storage.

#### (a) IF stage: a remark to leave the stage

[0177]. The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103:

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[0178]\* .The instruction-type identifier:111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second address "0100", which is the address of the extended register E4, and a destination register address "0110", . which is the address of the extended register E6.

[0179] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction as a post-increment memory-to-register transfer instruction that data should be read out from a memory address of the extended register E4 and then stored in the extended register E6 and the value of the extended register E4 should be increased by "4" after the storage, thereby producing an associated control signal.

[0172]

The contents of the extended register E4, [0180] associated with the physical address "0100", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

#### (c) EX stage

The operation unit 133 reads out the data [0181] stored in the E0 register 131 and outputs the data to an address input section of the data memory 143 in response to the control signal supplied from the operation decoder 116. Also, the operation unit 133 adds "4" to the data read out, and stores the sum in the MO register 141.

#### (d) MEM stage

[0182] . The data stored in the M0 register 141 is and [0189] passed through the data; memory 143 and then stored a set stored in the E0 register 131 and outputs the data to an in the W0 register 151. Also, responsive to the control 20 address input section of the data memory 143 in . signal supplied from the operation decoder 116, data is experies response to the control signal supplied from the operaread out from the data memory 143 at the specified and stion decoder 116. Also, the operation unit 133 adds "4" 151. The state of the transfer of the state of the state

ond instruction format that data should be read out from the and 151. the memory address of the extended register E5 and 1957 to the last the design of the part with the table the extended register E5 should be increased by "4" after the storage, where the second is the second of the second of the work of the storage of the work of the second of the storage.

[0185] The instruction fetch section 102 reads out the [0192] Instruction 8 LGE is an instruction in the Wist [0192] instruction from the instruction memory 101 and then a mainstruction format that if the result of subtraction perstores the instruction in the instruction register 103.

and a second second

#### (b) DEC stage

[0186] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "0101", which is the address of the extended register E5, and a destination register address "0001", which is the address of the extended register E1.

[0187] Responsive to the control signal supplied from the instruction-type identifier 111, the first register

address selector 117 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction as a post-increment memory-to-register transfer instruction that data should be read out from the memory address of the extended register E5 and then stored in the extended register E1 and the value of the extended register E5 should be increased by "4" after the storage, thereby producing an associated control signal.

The contents of the extended register E5, [0188] associated with the physical address "0101", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

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#### (c) EX stage

The operation unit 133 reads out the data memory address, and then stored in the W0 registers with to the data read out, and stores the sum in the M0 reg- or the

#### (e) WB stageがたま キュッ ひょa とど しゅがから おおく キーボード (d) MEM stage

with the state of the state of [0183] : The data stored in the W0 register 151 is read (a) [0190] The data stored in the M0 register 141 is out and then stored in the register file 120 at the desti-to-and passed through the data memory 143 and then stored [4,4] nation address "0110" specified by the second register 30% in the W0 register 151. Also, responsive to the control address extractor 114. The definition of the state of the signal supplied from the operation decoder 116, data is [0184] Instruction 7 MOV (#4, E5+), E1 is a post-incre-ward read out from the data memory 143 at the specified a ment memory-to-register transfer instruction in the sec- with memory address, and then stored in the W0 register?

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13 O. Life Landerstand and A. et al. and then stored in the register file 120 at the desti-(a) IF stage (a) 1. (b) 1. (c) 1. (c) 1. (d) 1. (e) to the control of the

> formed to execute Instruction 4 is equal to or larger than and are 2. 45 3"0", then a loop instruction should be executed by 25 33 changing the value of the program counter 124 into an address LOOP shown in Figure 14 above Instruction 1.

#### (a) IF stage

[0193] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0194] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to iden-

tify the type of this instruction as the first instruction format and output a control signal indicative of the type to the first register address selector 117. The operation decoder 116 decodes the instruction as a loop instruction, thereby producing an associated control signal.

[0195] Responsive to the control signal supplied from the operation decoder 116, the value of the program counter 124 in the register file 120 is stored in the E0 register 131.

#### (c) EX stage

The operation unit 133 reads out the data [0196] stored in the E0 register 131 and stores the destination address of the loop in the M0 register 141 responsive to the control signal supplied from the operation decoder 116.

#### (d) MEM stage

passed through the data memory 143 and then stored marei addresses "00" and "11", which are the respective in the W0 register 151.

#### (e) WB stage

[0198] The data stored in the W0 register 151 is stored at the program counter 124 in the register file 120. [0199] say, the total code size of the instructions shown in Fig- orders converted 113, to the register file 120.

[0200] Figure 14 into associated instructions in the third shown in Figure 14 are merged into rewritten Instruction (a. 2 othereby producing an associated control signal. 4 DMACH\_SUB and Instructions 7 and 8 shown in Fig- 240.7 [0208] The contents of the data register D0, associure 14 are merged into rewritten Instruction 6 were ated with the physical address "1100", are read out as a

[0201] In Figure 15, Instruction 1 represents a half-inverse stored in the E0 register 131. And the contents of the word transfer instruction from a register to a memory in the calculation and a special section of the control o the first instruction format. Instruction 2 represents a 45 address "1011", are read out as another source operhalf-word swap instruction (swap) in the second instruction format. Instruction 3 represents a half-word transfer instruction from a register to a memory in the second instruction format. Instruction 4 represents an instruction that a dual half-word multiply-and-accumulate operation and subtraction of an immediate value should be executed in parallel to each other. Instruction 5 represents a memory-to-register transfer instruction in the second instruction format. And Instruction 6 represents an instruction that memory-to-register data transfer and conditional branch should be executed in parallel to each other.

[0202] Hereinafter, specific times of operations will be

described.

[0203] Instruction 1 MOVH D0, (#-6, A3) is a registerto-memory transfer instruction (store) in the first instruction format that a value in the data register D0 should be stored at a memory address obtained by subtracting "6" from an address stored in the address register A3.

#### (a) IF stage

[0204] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0205] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to iden-48 (6) tify the type of this instruction as the first instruction forand with some mat and output a control signal indicative of the type to The data stored in the M0 register 141/is: (133) address extractor 112 extracts source register the management of addresses of the data register D0 and the address reg-43 Mass ister A3. The register address converter 113 converts 25 the address "00" of the data register **D0** and the address water # 7.504 to 111" of the address register A3 into 4-bit addresses "1100" and "1011", respectively.

16(11) [0206] Responsive to the control signal supplied from Instructions 3 and 5 rare composed of four phytes) address i selector 117 cutputs the prespective 4-bit Instructions 1, 2, 4, 6 and 7 are composed of three bytes and addresses "1100" and "1011" of the data and address and Instruction 8 is composed of one byte. That is to, the registers D0 and A3, supplied from the register address

133 [0207] A. The operation decoder 116 decodes the Figure 15 illustrates respective instructions 35 instruction as a register-to-memory transfer instruction obtained by rewriting some of the instructions shown in 111(3) (store) that a value in the data register D0 should be stored at a memory address obtained by subtracting "6" instruction format. Specifically, instructions 4 and 5% (a) from an address stored in the address register A3,

> Althorated the state of the source operand from the register file 120 and then and from the register file 120 and then stored in the E1 register 132.

#### (c) EX stage

The data stored in the E0 register 131 is [0209] passed through the operation unit 133 and then stored in the M0 register 141. In response to the control signal supplied from the operation decoder 116, the operation unit 133 subtracts "6" from the address stored in the E1 register 132 and outputs the result of subtraction to an address input section of the data memory 143.

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#### (d) MEM stage

[0210] The data stored in the M0 register 141 is stored in the data memory 143 at an address specified by the result of subtraction performed by the operation unit 133.

#### (e) WB stage

[0211] No operations are performed.

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[0212] Instruction 2 SWHW E0, E2 is an instruction in the second instruction format that data, obtained by swapping the upper and lower half words of the data stored in the extended register E0, should be stored in the extended register E2.

### (a) IF stage

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[0213] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

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#### (b) DEC stage

[0214] The instruction-type identifier 111 decodes the 25 instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "0000", which is the address of the extended register E0, and a destination register address "0010", 1011 which is the address of the extended register E2.

[0215] Responsive to the control signal supplied from Access the instruction-type identifier 111, the first register 35° address selector 117 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction to find that data, obtained by swapping the upper and lower half words of the data stored in the 40 extended register E0, should be stored in the extended register E2, thereby producing an associated control signal. \*

The contents of the extended register E0, associated with the physical address "0000", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

#### (c) EX stage

[0217] Responsive to the control signal supplied from the operation decoder 116, the operation unit 133 performs a swapping operation on the data stored in the E0 register 131 by swapping the upper and lower half words thereof. Then, the result of this operation is stored in the M0 register 141.

#### (d) MEM stage

The data stored in the M0 register 141 is [0218] passed through the data memory 143 and then stored in the W0 register 151.

#### (e) WB stage

[0219] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0010" specified by the second register address extractor 114.

[0220] Instruction 3 MOVH E2, (#-4, A3) is a registerto-memory transfer instruction (store) in the second instruction format that a value in the extended register E2 should be stored at a memory address obtained by subtracting "4" from an address stored in the address register A3.

#### (a) IF stage

[0221] The instruction fetch section 102 reads out the 35 instruction from the instruction memory 101 and then [89] stores the instruction in the instruction register 103. ng innggin sa led mandam kilebokin, in kultuar na

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#### (b) DEC stage regular regional action of the control of the contr

[0222] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The first register address extractor 112 extracts a source register address "11", which is the address of the address register A3. The second register address extractor 114 extracts another source register address "0010", which is the address of the extended register E2. The register address converter 113 converts the address "11" of the address register A3 into a 4-bit address "1011".

[0223] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the 4-bit address "1011" 11.5 of the address register A3, supplied from the register address converter 113, and the 4-bit address "0010" of the extended register E2 to the register file 120.

The operation decoder 116 decodes the instruction as a register-to-memory transfer instruction (store) that a value in the extended register E2 should be stored at a memory address obtained by subtracting "4" from an address stored in the address register A3, thereby producing an associated control signal.

The contents of the extended register E2, [0225] associated with the physical address "0010", are read out as a source operand from the register file 120 and then stored in the E0 register 131. And the contents of the address register A3, associated with the physical address "1011", are read out as another source operand from the register file 120 and then stored in the E1

register 132.

#### (c) EX stage

The data stored in the E0 register 131 is [0226] passed through the operation unit 133 and then stored in the M0 register 141. In response to the control signal supplied from the operation decoder 116, the operation unit 133 subtracts "4" from the address stored in the E1 register 132 and outputs the result of subtraction to an address input section of the data memory 143.

#### (d) MEM stage

[0227] The data stored in the M0 register 141 is stored 15 in the data memory 143 at an address specified by the result of subtraction performed by the operation unit

#### (e) WB stage

[0228] No operations are performed.

[0229] Instruction 4 DMACH\_SUB E6, E1, 1, E3 is an experience. instruction in the third instruction format, and is company to posed of two units to be executed in parallel to each 25 other. One of these units is an instruction that a product of the data obtained by multiplying together respective upper half words of the data stored in the extended registers E6 man same time, the operation unit 133 extracts and multiand E1 should be added to a product obtained by multi-compaplying together respective lower half words thereof, and easier data stored in the E0 and E1 registers 131, and 132. the sum should be accumulated in the extended register, and a E1. The other unit is an instruction that "1" should be a transfer or the contract of the cont subtracted from the data stored in the extended register Control of the State of Attitude

#### (a) IF stage

[0230] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

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#### (b) DEC stage

[0231] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to iden- 45 tify the type of this instruction as the third instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "0110", which is the address of the extended register E6, and a destination register address "0001", which is the address of the extended register E1. In addition, the third register address extractor 115 extracts "0011" as a source/destination register address, i.e., the address of the extended register E3. [0232] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied

from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction to find that a product obtained by multiplying together respective upper half words of the data stored in the extended registers E6 and E1 should be added to a product obtained by multiplying together respective lower half words thereof, and the sum should be accumulated in the extended register E1, thereby producing an associated control signal.

The contents of the extended register E6, [0233] associated with the physical address "0110", are read out as a source operand from the register file 120 and then stored in the E0 register 131. And the contents of the extended register E1, associated with the physical address "0001", are read out as another source operand from the register file 120 and then stored in the E1 register 132. In parallel to these operations, the contents of the extended register E3, associated with the physical address "0011", are read out as still another source operand from the register file 120 and then stored in the E2 register 134.

#### (c) EX stage

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[0234]. The operation unit 133 extracts and multiplies stored in the E0 and E1 registers 131 and 132. At the plies together the respective lower half words of the These two products are added to the data stored in the E1 register 132. And the sum is stored in the M0 register. 141. In parallel thereto, the operation unit 133 also reads out the data stored in the E2 register 134 and subtracts "1" therefrom. And the result of subtraction is stored in the M1 register 142:

#### (d) MEM-stage

[0235] The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151. Also, the data stored in the M1 register 142 is passed through the data memory 143 and then stored in the W1 register 152.

### (e) WB stage

[0236] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0001" specified by the second register address extractor 114. In parallel thereto, the data stored in the W1 register 152 is read out and then stored in the register file 120 at the destination address "0011" specified by the third register address extractor 115. [0237] Instruction 5 MOV (#4, E4+), E6 is a post-increment memory-to-register transfer instruction in the second instruction format that data should be read out from a memory address of the extended register E4 and then

stored in the extended register E6 and the value of the extended register E4 should be increased by "4" after the storage.

#### (a) IF stage

[0238] The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

#### (b) DEC stage

[0239] The instruction-type identifier 111 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the second instruction format and output a control signal indicative of the type to the first register address selector 117. The second register address extractor 114 extracts a source register address "0100", which is the address of the extended register E4, and a destination register address "0110", which is the address of the extended register E6.

[0240] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses; supplied from the second register address extractor 114, to the 25 register file 120. The operation decoder 116 decodes the instruction as a post-increment memory-to-register transfer instruction that data should be read out from a memory address of the extended register E4 and then stored in the extended register E6 and the value of the 30 extended register E4 should be increased by "4" after the storage, thereby producing an associated control signal.

[0241] The contents of the extended register E4, associated with the physical address "0100", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

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#### (c) EX stage of the special of the same with an of

[0242] The operation unit 133 reads out the data stored in the E0 register 131 and outputs the data to an address input section of the data memory 143 in response to the control signal supplied from the operation decoder 116. Also, the operation unit 133 adds "4" to the data read out, and stores the sum in the M0 register 141.

#### (d) MEM stage

[0243] The data stored in the M0 register 141 is passed through the data memory 143 and then stored in the W0 register 151. Also, responsive to the control signal supplied from the operation decoder 116, data is read out from the data memory 143 at the specified memory address and then stored in the W0 register 151.

#### (e) WB stage

[0244] The data stored in the W0 register 151 is read out and then stored in the register file 120 at the destination address "0110" specified by the second register address extractor 114.

[0245] Instruction 6 MOV\_LGE (#4, E5+), E1 is an instruction in the third instruction format and is composed of two units to be executed in parallel to each other. One of these two units is a post-increment memory-to-register transfer instruction that data should be read out from a memory address of the extended register E5 and then stored in the extended register E1 and the value of the extended register E5 should be increased by "4" after the storage. The other unit is an instruction that if the result of subtraction performed to execute Instruction 4 is equal to or larger than "0", then a loop instruction should be executed by changing the value of the program counter 124 into an address LOOP shown in Figure 15 above Instruction 1.

#### (a) IF stage

[0246]. The instruction fetch section 102 reads out the instruction from the instruction memory 101 and then stores the instruction in the instruction register 103.

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#### (b) DEC stage

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[0247]. The instruction-type identifier 1.11 decodes the instruction stored in the instruction register 103 to identify the type of this instruction as the third instruction format and output a control signal indicative of the type to the first register address selector 1.17. The second register address extractor 1.14 extracts a source register address "0.101", which is the address of the extended register E5, and a destination register address "0.001", which is the address of the extended register E1.

[0248] Responsive to the control signal supplied from the instruction-type identifier 111, the first register address selector 117 outputs the addresses, supplied from the second register address extractor 114, to the register file 120. The operation decoder 116 decodes the instruction as a post-increment memory-to-register transfer instruction that data should be read out from a memory address of the extended register E5 and then stored in the extended register E1 and the value of the extended register E5 should be increased by "4" after the storage, thereby producing an associated control signal.

[0249] The contents of the extended register E5, associated with the physical address "0101", are read out as a source operand from the register file 120 and then stored in the E0 register 131.

[0250] Furthermore, the operation decoder 116 decodes the other unit as a loop instruction, thereby producing an associated control signal.

[0251] Responsive to the control signal supplied from

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the operation decoder 116, the value of the program counter 124 in the register file 120 is stored in the E2 register 134.

#### (c) EX stage

[0252] The operation unit 133 reads out the data stored in the E0 register 131 and outputs the data to an address input section of the data memory 143 in response to the control signal supplied from the operation decoder 116. Also, the operation unit 133 adds "4" to the data read out, and stores the sum in the M0 register 141.

[0253] On the other hand, the operation unit 136 reads out the data stored in the E2 register 134 and stores the destination address of the loop in the M1 register 142 responsive to the control signal supplied from the operation decoder 116.

#### (d) MEM stage

[0254] The data stored in the M0 register 141 is a case Clapassed through the data memory 143 and then stored in the W0 register 151. Also, responsive to the control case 1. signal supplied from the operation decoder 115, data is case read out from the data memory 143 at the specified memory address and then stored in the W0 register 151.

[0255] Also, the data stored in the M1 register 142 is passed through the data memory 143 and then stored in the W1 register 152.

. . . . . .

#### (e) WB stage

, . .

[0256] The data stored in the W0 register 151 is read: 055 out and then stored in the register file 120 at the destination address "0001" specified by the second register.

[0257] On the other hand, the data stored in the W1 register 152 is stored at the program counter 124 in the register file 120.

[0258] Among the instructions shown in Figure 15, Instructions 3, 4, 5 and 6 are composed of four bytes, while Instructions 1 and 2 are composed of three bytes. That is to say, the total code size of the instructions shown in Figure 15 is 22 bytes.

[0259] As can be understood, by executing some instructions in the third instruction format according to this embodiment, the code size can be reduced from 24 to 22 bytes. Also, by changing the instruction set shown in Figure 14 into that shown in Figure 15, the number of instructions can also be reduced from eight to six, thus improving the performance in executing the instructions.

[0260] It should be noted that the present invention is in no way limited to the data processor described in the foregoing embodiment. For example, although address and data registers are extended in the foregoing embodiment, general-purpose registers may be

extended instead. Also, in the foregoing description, the respective numbers of address, data and extended registers are four, four and eight. Alternatively, any number of registers may be used for each of these types. Moreover, in the foregoing embodiment, the first register file 220 is specified in the first instruction format, while the second register file 120, including the first register file 220, is specified in the second instruction format. However, the present invention is not limited to such a specific embodiment. The number of registers included in the second register file may be larger than that of registers included in the first register file, and only the second register file may be specified in the second instruction format without specifying the first register file.

[0261] in Furthermore, in accordance with the third instruction format, two units are supposed to be executed in parallel to each other in the foregoing embodiment. If necessary, it is naturally possible to execute three or more units in parallel to each other in accordance with the third instruction format.

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William Broken

CAR GRADER OF STANDING MANAGER

#### Claims

 A data processor for executing an instruction described in a first instruction format and an instruction described in a second instruction format, wherein the first instruction format defines a register-addressing field of a predetermined size, while the second instruction format defines a registeraddressing field of a size larger than the size of the register-addressing field defined by the first instruction format, and

wherein the data processor comprises:

94.14

- means, responsive to an instruction, for identifying the received instruction as being described in the first or second instruction format by the instruction itself;
- a first register file including a plurality of registers; and
- a second register file also including a plurality of registers, the number of the registers included in the second register file being larger than the number of the registers included in the first register file,
- wherein if the identifying means has identified the received instruction as being described in the first instruction format, the data processor executes the instruction using data held in the first register file,
- while if the identifying means has identified the received instruction as being described in the second instruction format, the data processor executes the instruction using data held in the second register file.
- The data processor of Claim 1, wherein the first instruction format defines a number of instruction

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fields and the second instruction format defines another number of instruction fields, and wherein the identifying means identifies the received instruction as being described in the first or second instruction format by the contents of at least one of the instruction fields of the instruction that is defined by at least one predetermined ordinal number.

- The data processor of Claim 2, wherein the number of the instruction fields defined by the second instruction format is larger than the number of the instruction fields defined by the first instruction format
- 4. The data processor of Claim 2, wherein the predetermined ordinal number of the instruction field used by the identifying means for format identification is first.

. Kan 12. . .

. . . . .

5. The data processor of Claim 2, wherein the predetermined ordinal numbers of the respective instruction fields used by the identifying means for format identification are first and second.

and the second

- 6. The data processor of Claim 2; wherein the instructions described in the first and second instruction formats are variable-length instructions of the control of the con
- 7. The data processor of Claim 2, wherein in the first instruction format, the register-addressing field is included in the instruction field that is defined by the predetermined ordinal number and used by the identifying means for format identification, and wherein in the second instruction format, the register-addressing field is not included in the instruction field that is defined by the predetermined ordinal number and used by the identifying means for format identification.
- 8. The data processor of Claim 2, wherein in the first instruction format, operation and length of an instruction to be executed or only the length of the instruction are/is specified in a first one of the instruction fields, and only operations of the instruction to be executed are specified in succeeding ones of the instruction fields.

- 9. The data processor of Claim 2, wherein in the second instruction format, only length of an instruction to be executed is specified in a first one of the instruction fields, and only operations of the instruction to be executed are specified in succeeding ones of the instruction fields.
- 10. The data processor of Claim 1 or 2, wherein the second register file includes all of the registers included in the first register file.

- 11. The data processor of Claim 1 or 2, wherein an address described in the first instruction format for specifying one of the registers included in the first register file is different from an address described in the second instruction format for specifying the same register.
- 12. The data processor of Claim 11, further comprising an address converter, wherein responsive to an instruction, the address converter converts an address described in the first instruction format, which has been specified by the

converter converts an address described in the first instruction format, which has been specified by the instruction to access one of the registers included in the first register file, into an address of the register described in the second instruction format, and wherein if the identifying means has identified the received instruction as being described in the first instruction format, then the address, converted by the address converter, is output to the first register file.

- 13. The data processor of Claim 2, wherein the first instruction format defines an instruction field specifying operation of the instruction and an address of one of the registers included in the first register file.
- 14. The data processor of Claim 2, wherein the second instruction format defines an instruction field specifying only operation of the instruction and another instruction field specifying only an address of at least one of the registers included in the first and second register files.
- 16. The data processor of Claim 1 or 2, further executing an instruction described in a third instruction format, wherein the third instruction format specifies a clurality of operations and defines a register-addressing field of a size larger than that of the register-addressing field defined by the first instruction format, the register-addressing field defined by the third instruction format being used to specify one of the registers included in the second register file, and

wherein responsive to an instruction, the identifying means identifies the received instruction as being described in the third instruction format by the instruction itself.

17. The data processor of Claim 16, wherein the third instruction format defines: an instruction field specifying a plurality of operations to be executed follow-

ing an instruction; and another instruction field addressing one of the registers included in the second register file.

- 18. The data processor of Claim 16, further comprising 5 a plurality of operation units for executing in parallel the operations specified by the instruction described in the third instruction format.
- 19. The data processor of Claim 16, wherein an . 10 instruction described in the third instruction format is an instruction described in the second instruction format that is frequently specified.
- 20. The data processor of Claim 16, wherein the number of bits of each of operation-specifying. fields, which are defined by the third instruction for-, mat for specifying operations of an instruction to be executed in parallel to each other, is smaller than the number of bits of an operation-specifying field 20 defined by the second instruction format.
- 21. The data processor of Claim 16, wherein an address, described in the second instruction format for specifying one of the registers included in the 25 second register file, is the same as an address described in the third instruction format for specifying the same register.
- 22. A data processor for executing an instruction 30 described in a first instruction formal and an a instruction described in a second instruction format, the data processor comprising:

a register file including a predetermined 35 number of registers, an address described in the first instruction format for specifying one of the registers being different from an address in described in the second instruction format for specifying the same register; .... an address converter for receiving the instruction described in the first instruction format and converting an address described in the first instruction format, specified by the instruction to access one of the registers, into an address described in the second instruction format; and means, responsive to an instruction, for identifying the received instruction as being described in the first or second instruction format by the instruction itself, wherein the output of the address converter is controlled by the output of the identifying

23. An instruction format for use in defining an arrangement of an instruction to be executed by a data processor, the instruction format being implemented as first and second instruction formats,

wherein the first instruction format defines a number of instruction fields and the second instruction format defines another number of instruction fields, the number of the instruction fields defined by the second instruction format being larger than the number of the instruction fields defined by the first instruction format, and wherein at least one of the instruction fields that are defined by the first and second instruction formats is used to identify the type of the instruction to be executed as being described in the first or second instruction format, and wherein the first instruction format defines a register-addressing field of a predetermined size, while the second instruction format defines a registeraddressing field of a size larger than the size of the register-addressing field defined by the first instruc-

24. The instruction format of Claim 23, implemented as a third instruction format, wherein the third instruction format defines still another number of instruction fields, the number of the instruction fields defined by the third instruction informat being larger than the number of the instruction fields defined by the first instruction format, and wherein the third instruction format defines a register-addressing field of a size larger than the size of the register-addressing field defined by the first instruction format, and wherein at least one of the instruction fields that is defined by the third instruction format is used to identify the type of the instruction to be executed as being described in the third instruction format, and wherein the third instruction format describes a plurality of operations to be executed.

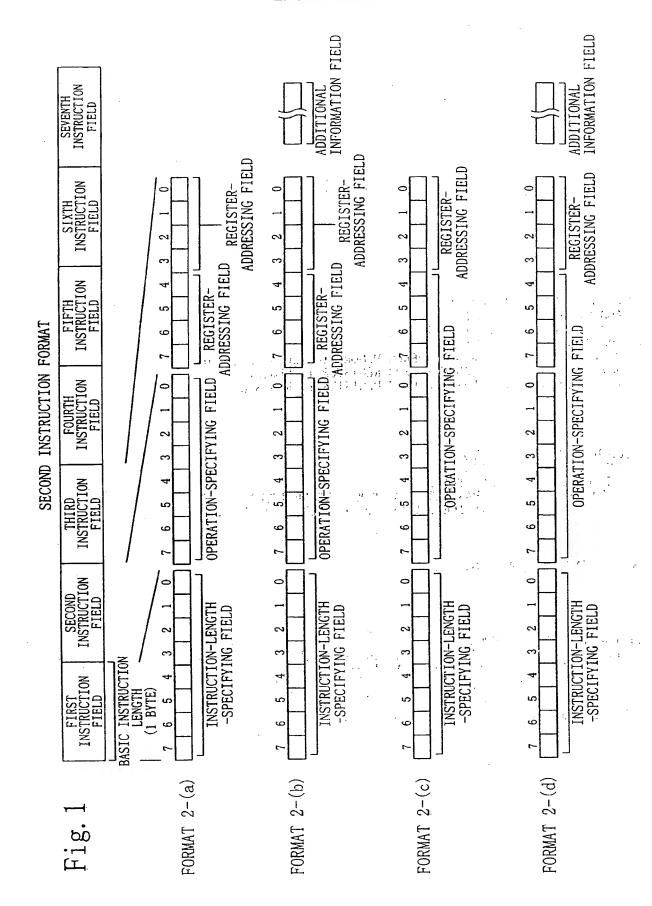
tion format.

25. The instruction format of Claim 23 or 24; wherein the instruction field used to identify the type of the instruction to be executed is a first one of the instruction fields.

Company of the second second

26. The instruction format of Claim 23 or 24, wherein the instruction fields used to identify the type of the instruction to be executed are first and second ones of the instruction fields.

]



## Fig. 2

SECOND INSTRUCTION FORMAT (a)

: ADD

: SUBTRACT

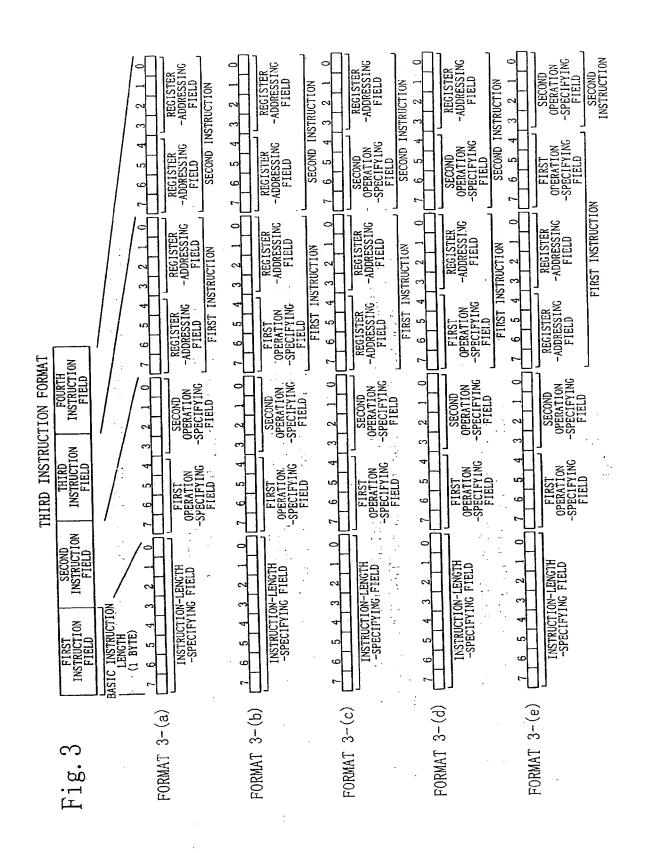
: COMPARE

ADD Rm, Rn

SUB Rm, Rn

CMP Rm, Rn

```
MOV (Rm), Rn
                   : TRANSFER FROM MEMORY TO REGISTER (LOAD)
                   : TRANSFER FROM REGISTER TO MEMORY (STORE)
 MOV Rm, (Rn)
                   : TRANSFER FROM REGISTER TO REGISTER
 MOV Rm, Rn
SECOND INSTRUCTION FORMAT (b)
                : ADD
 ADD Rm, Rn, Rd
                   : SUBTRACT
 SUB Rm, Rn, Rd
                   : TRANSFER FROM MEMORY TO REGISTER (LOAD)
 MOV (Ri, Rm), Rn
                     INDIRECTLY BY WAY OF INDEXED REGISTER
SECOND INSTRUCTION FORMAT (c)
SECOND INSTRUCTION FORMAT (d)
                   : ADD 16-BIT IMMEDIATE VALUE
 ADD imm 16, Rn
                   : ADD 16-BIT IMMEDIATE VALUE
 ADD imm 16, Rn
 MOV(disp8, SP), Rn : TRANSFER FROM MEMORY TO REGISTER (LOAD)
                     BY ADDRESSING USING STACK POINTER (SP) WITH DISPLACEMENT
 MOV Rm, (disp8, SP): TRANSFER FROM REGISTER TO MEMORY (STORE)
                     BY ADDRESSING USING STACK POINTER (SP) WITH DISPLACEMENT
```

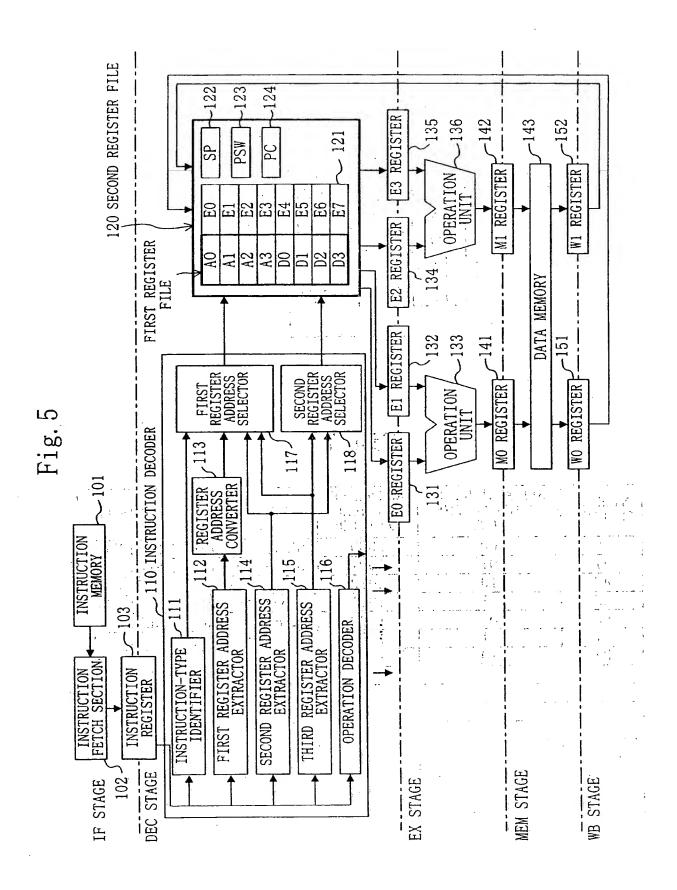


# Fig. 4

: ADD BETWEEN REGISTERS AND ADD BETWEEN REGISTERS IN PARALLEL : SUBTRACT BETWEEN REGISTERS AND SHIFT BETWEEN REGISTERS IN PARALLEL	: ADD IMM : SUBTRAC		IIRD INSTRUCTION FORMAT (d) ADD_ADD imm4, Rn1, imm4, Rn2 : ADD IMMEDIATE VALUE TO REGISTER AND ADD IMMEDIATE VALUE TO REGISTER IN PARALLEL SUB_ADD imm4, Rn1, imm4, Rn2 : SUBTRACT IMMEDIATE VALUE FROM REGISTER AND ADD IMMEDIATE VALUE TO REGISTER IN PARALLEL
THIRD INSTRUCTION FORMAT (a) ADD_ADD Rml, Rnl, Rm2, Rn2 SUB_ASL Rml, Rnl, Rm2, Rn2	THIRD INSTRUCTION FORMAT (b) ADD_ADD imm4, Rn1, Rm2, Rn2 SUB_ASL imm4, Rn1, Rm2, Rn2	THIRD INSTRUCTION FORMAT (c) ADD_ADD Rml, Rnl, imm4, Rn2 DMACH_SUB Rml, Rnl, imm4, Rn2	THIRD INSTRUCTION FORMAT (d) ADD_ADD imm4, Rn1, imm4, Rn2 SUB_ADD imm4, Rn1, imm4, Rn2

TRANSFER BETWEEN REGISTERS AND CONDITIONAL LOOP IN PARALLEL

THIRD INSTRUCTION FORMAT (e) MOV\_Lcc(Rm+, imm4), Rn



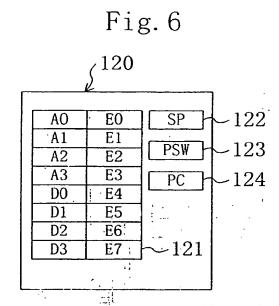


Fig. 7

NAME OF REGISTER	BIT ASSIGNMENT ON INSTRUCTION CODE	NUMBER OF PHYSICAL REGISTER	NAME OF PHYSICAL REGISTER
AO	00	1000	GENERAL-PURPOSE REGISTER
A1	01	1001	GENERAL-PURPOSE REGISTER
A2 .	· 10	1010	GENERAL-PURPOSE REGISTER
A3	11	1011	GENERAL-PURPOSE REGISTER
DO	00	1100	GENERAL-PURPOSE REGISTER
D1	01	1101	GENERAL-PURPOSE REGISTER
D2	10	1110	GENERAL-PURPOSE REGISTER
D3	11	1111	GENERAL-PURPOSE REGISTER
EO ·			
E1 -			
E2			,
E3			
E4			
E5	7		
E6 ·			
E7			

Fig. 8

		NURSER OF	
NAME OF	BIT ASSIGNMENT	NUMBER OF	MAME OF DUVCTOM DECICED
REGISTER	ON INSTRUCTION	PHYSICAL	NAME OF PHYSICAL REGISTER
KEGIGIEK	CODE	REGISTER	
AO	1000	1000	GENERAL-PURPOSE REGISTER
A1	1001	1001	GENERAL-PURPOSE REGISTER
A2	1010	1010	GENERAL-PURPOSE REGISTER
A3	1011	1011	GENERAL-PURPOSE REGISTER
DO	1100	1100	GENERAL-PURPOSE REGISTER
D1	1101	1101	GENERAL-PURPOSE REGISTER
D2	1110	1110	GENERAL-PURPOSE REGISTER
D3	1111	1111	GENERAL-PURPOSE REGISTER
EO	0000	0000	GENERAL-PURPOSE REGISTER
E1	> 0001	0001	GENERAL-PURPOSE REGISTER
E2	0010	0010	GENERAL-PURPOSE REGISTER
E3	0011	0011	GENERAL-PURPOSE REGISTER
E4	0100	0100 t 👍	GENERAL-PURPOSE REGISTER
E5	0101	0101	GENERAL-PURPOSE REGISTER
E6	0110	0110	GENERAL-PURPOSE REGISTER
E7	0111	0111	GENERAL-PURPOSE REGISTER

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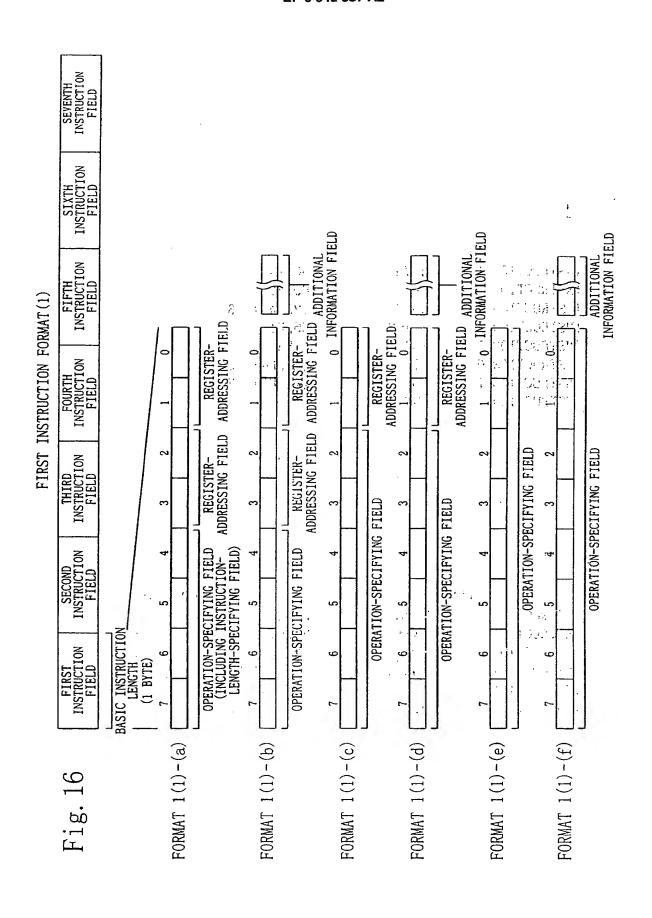
Fig. 9 a=a+b c=c+d Fig. 10 INSTRUCTION 1 ADD D1, DO **INSTRUCTION 2** ADD D2, D3 MOV (#4, SP), DO MOV (#8, SP), D1 Fig. 11 INSTRUCTION 1 INSTRUCTION 2 ADD D1, D0 MOV D0, (#4, SP) MOV (#12, SP), D0 INSTRUCTION 3 INSTRUCTION 4. INSTRUCTION 5 INSTRUCTION, 6 MOV (#16, SP), D1 INSTRUCTION 7 ADD D1, DO. MOV DO, (#12, SP) MOV DO, (#20, SP) INSTRUCTION 1 MOV D1, (#24, SP) MOV (#4, SP), D0 MOV (#8, SP), D1 INSTRUCTION 4 INSTRUCTION 5 ADD D1, DO MOV DO, (#4, SP) INSTRUCTION 6 MOV (#12, SP), DO INSTRUCTION 7 MOV (#16, SP), D1 INSTRUCTION 8 ADD D1, D0 INSTRUCTION 9 MOV DO, (#12, SP) ... INSTRUCTION 10 INSTRUCTION 11 MOV (#20, SP), DO INSTRUCTION 12 MOV (#24, SP), D1 Fig. 13 INSTRUCTION 1 ADD E1, E0 INSTRUCTION 2 ADD E2, E3

# Fig. 14

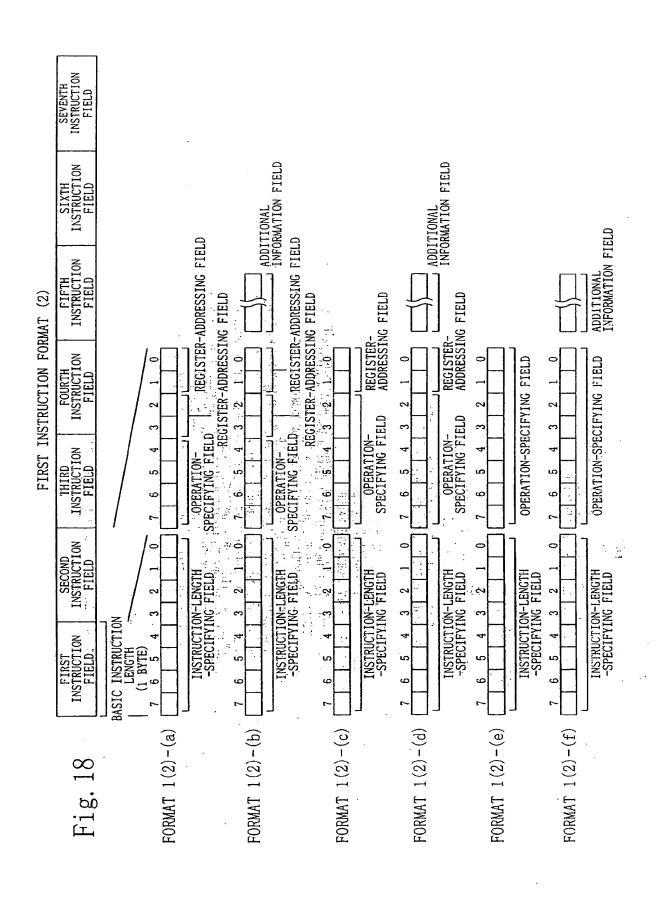
LOOP		•	CODE SIZE(BY	TE)
INSTRUCTION 1	MOVH	DO, (#-6, A3)	3	
INSTRUCTION 2	SWHW	E0, E2	3	
INSTRUCTION 3	MOVH	E2, (#-4, A3)	4	
INSTRUCTION 4	DMACH	E6, E1	3	. •
INSTRUCTION 5	SUB	1, E3	4	
INSTRUCTION 6	MOV	(#4, E4+), E6	3	
INSTRUCTION 7	MOV	(#4, E5+), E1	3	
INSTRUCTION 8	LGE		• • • • • • • • • • • • • • • • • • • •	

# Fig. 15

	LOOP		CODE	SIZE (BYT
INSTRUCTION	1	HVOM	DO, (#-6, A3)	3 '
INSTRUCTION	2	SWHW	E0, E2	3
INSTRUCTION	3	MOVH	E2, (#-4, A3)	4
INSTRUCTION	4	DMACH_SUB	E6, E1, 1, E3	4
INSTRUCTION	5	MOV	(#4, E4+), E6	4
INSTRUCTION	6	MOV_LGE	(#4, E5+), E1	4 .



```
ALUE
A FROM REGISTER TO MEMORY (STORE)
FIRST INSTRUCTION FORMAT (1)-(b)
                                                                                                                                                                                                                                                                                                                                           MOV Dm, (abs16)
MOVBU Dm, (abs16)
                                                                                                                                                                                                                                                                                                                MOVHU (abs16), Dn
                                                                                                                                                                                                                                                                                                                                                                                        MOVHU Dm (abs16)
```



# Fig. 19

FIRST INSTRUCTION FORMAT (2)-(a)
SUB Dm, Dn : SUBTRACT
MOV(Am), An : TRANSFER FROM MEMORY TO REGISTER (LOAD)
MOV Am, (An) : TRANSFER FROM REGISTER TO MEMORY (STORE)

FIRST INSTRUCTION FORMAT (2)-(b)
MOV(Ai, Dn), Dn : TRANSFER FROM MEMORY TO REGISTER (LOAD)
... INDIRECTLY BY WAY OF INDEXED REGISTER

FIRST INSTRUCTION FORMAT (2)-(¢)

FIRST INSTRUCTION FORMAT (2)-(d)
ADD imm16, An : ADD 16-BIT IMMEDIATE VALUE
ADD imm16, Dn : ADD 16-BIT IMMEDIATE VALUE:

FIRST INSTRUCTION FORMAT (2)-(e)
RTI : RETURN FROM INTERRUPT STATE

FIRST INSTRUCTION FORMAT (2)-(f)

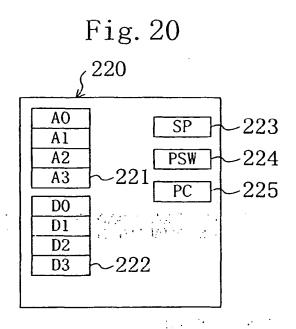


Fig. 21

NAME OF REGISTER	BIT ASSIGNMENT ON INSTRUCTION CODE	NUMBER OF PHYSICAL REGISTER	NAME OF PHYSICAL REGISTER
AO	00	00	ADDRESS REGISTER
A1	01	01	ADDRESS REGISTER
A2	02	02	ADDRESS REGISTER
A3	03	03	ADDRESS REGISTER
DO	00	00	ADDRESS REGISTER
D1	01	01	ADDRESS REGISTER
D2	02	02	ADDRESS REGISTER
D3	03	03	ADDRESS REGISTER

Fig. 22(a)
Prior Art

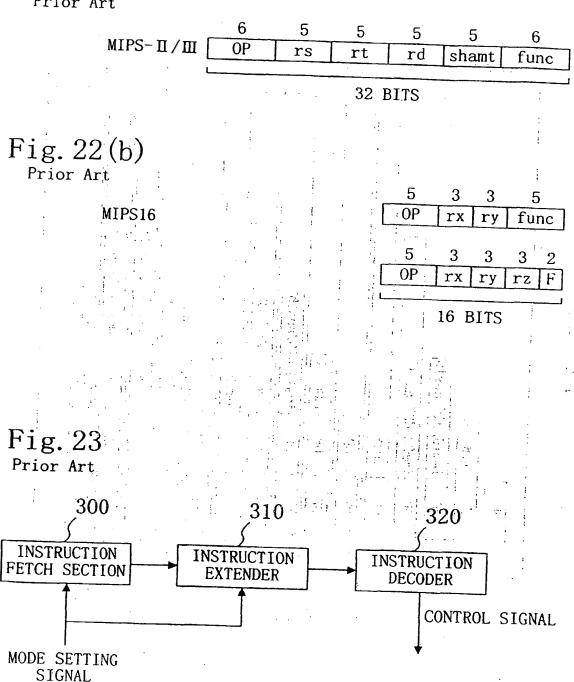


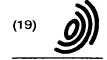
Fig. 24

4				
	] os	do		BIT CODES IN
FIRST	S1	8	imm8/d8	FIRST BYTE (HEXADECIMAL
FORMAT	] ZS	පි	imm16/d16/abs16	NUMBER)
(1)	S4 [	g	imm32/d32/abs32	00~EF
	] 9 <u>s</u>	g	imm48	
	20	g	0P	F0~F4, F6
FIRST	10	g	OP [imm8/d8]	F8
INSTRUCTION	02	g.	OP   imm16/d16/abs16	FA
(2)	04	G)	OP [imm32/d32/abs32	FC
	D2 [	g	OP   imm40	F5
	] []	용	OP OP	F9
SECOND	TI	ď	OP OP imm8/d8	FB
FORMAT	T3	g	OP OP imm24/d24/abs24	FD
	T4	P	OP OP imm32/d32/abs32	표
THIRD	0%	g	0P 0P 0P	F7
FORMAT				

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EP 0 942 357 A3

(12)

### **EUROPEAN PATENT APPLICATION**

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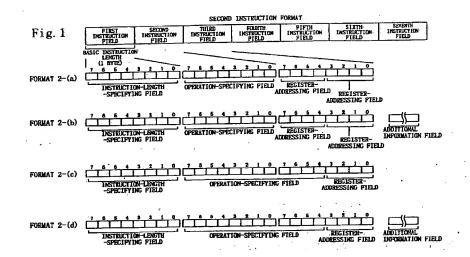
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### (54) Data processor compatible with a plurality of instruction formats

A data processor according to the present invention executes instructions described in first and second instruction formats. The first instruction format defines a register-addressing field of a predetermined size, while the second instruction format defines a register-addressing field of a size larger than that of the register-addressing field defined by the first instruction format. The data processor includes: instruction-type identifier, responsive to an instruction, for identifying the received instruction as being described in the first or second instruction format by the instruction itself; a first register file including a plurality of registers; and a second register file also including a plurality of registers, the number of the registers included in the second register file being larger than that of the registers included in the first register file. If the instruction-type identifier has identified the received instruction as being described in the first instruction format, the data processor executes the instruction using data held in the first register file. On the other hand, if the instruction-type identifier has identified the received instruction as being described in the second instruction format, the data processor executes the instruction using data held in the second register file.

#### EP 0 942 357 A3





### **EUROPEAN SEARCH REPORT**

Application Number

EP 99 10 4620

		ERED TO BE RELEVANT	Dalayant	OL ASSISTATION OF THE
Category	Citation of document with in of relevant pass	idication, where appropriate, ages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.CI.6)
X	WO 97 48041 A (LSI 18 December 1997 (1		1-4, 7-14,22, 23,25	G06F9/30 G06F9/318 G06F9/38
Y	* page 13, line 18 * page 14, line 6 -	- page 12, line 37 * - line 31 * line 21 * - page 22, line 12 *	15-18,21 24	
Υ	EP 0 425 410 A (IBM 2 May 1991 (1991-05 * column 4, line 52 figures 2-4 *		15-18,21	.*
Υ	EP 0 426 393 A (FUJ 8 May 1991 (1991-05		24	
Α	* the whole documen		15-18,21	
A	without increasing Length"	-	1,10,22, 23	
i	IBM TECHNICAL DISCL	OSURE BULLETIN.,		TECHNICAL FIELDS SEARCHED (Int.Cl.6)
	pages 771-772, XP00 IBM CORP. NEW YORK. ISSN: 0018-8689 * the whole documen	, US		G06F
А	D. R. DITZEL ET AL. Architecture of the THE 14TH ANNUAL INT COMPUTER ARCHITECTU pages 309-319, XP00 pittsburg, pen. US	 : "The Hardware CRISP Microprocessor" ERNATIONAL SYMPOSIUM ON RE,June 1987 (1987–06),		
		-/		
	The present search report has			
	Place of search	Date of completion of the search	Dag.	Examiner kalakis, T
	THE HAGUE	19 January 2000		
X:par Y:par doc	CATEGORY OF CITED DOCUMENTS ticularly relevant if taken alone ticularly relevant if combined with another the same category.	E : earlier patent do after the filing do ther D : document cited L : document cited	cument, but publi ite in the application for other reasons	shed on, or
O:nor	hnological background n-written disclosure ermediate document	& ; member of the s document		

FPO FORM 1503 03 82 (5



### **EUROPEAN SEARCH REPORT**

Application Number

EP 99 10 4620

ategory	Citation of document with indication	on, where appropriate,	Relevant	CLASSIFICATION OF THE
андогу	of relevant passages		to claim	APPLICATION (Int.Cl.6)
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	6 May 1992 (1992-05-06)		· .	*
	* the whole document *			, and the second
١	WO 97 22924 A (EITAN BE	NNY ;KOWASHI EIICHI		
	(JP); PELEG ALEXANDER D			
	26 June 1997 (1997-06-2	6) :		
\	PATENT ABSTRACTS OF JAP	AN	15,17	-
	vol. 015, no. 075 (P-11	69),		
	21 February 1991 (1991- & JP 02 293932 A (NEC I	02-21)		
r	LTD), 5 December 1990 (	1990-12-05)	1.	
	* abstract *			ref ( ) ref ( )
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:				SEARCHED (Int.CL6)
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	The present search report has been	drawn up for all claims		
	Place of search	Date of completion of the search		Examiner
	THE HAGUE	19 January 2000	Das	kalakis, T
	CATEGORY OF CITED DOCUMENTS	T : theory or princip E : earlier patent do		
Х : ра	rticularly relevant if taken alone	after the filing do	ate	
do	nticularly relevant if combined with another current of the same category	L : document cited	for other reasons	
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Application Number

EP 99 10 4620

CLAIMS INCURRING FEES	
The present European patent application com	prised at the time of filing more than ten claims.
Only part of the claims have been pareport has been drawn up for the first been paid, namely claim(s):	aid within the prescribed time limit. The present European search st ten claims and for those claims for which claims fees have
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No claims fees have been paid within been drawn up for the first ten claim.	n the prescribed time limit. The present European search report has s.
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LACK OF UNITY OF INVENTION	the second of th
The Search Division considers that the prese requirements of unity of invention and relates	nt European patent application does not comply with the stop several inventions or groups of inventions, namely:
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All further search fees have been pa been drawn up for all claims.	aid within the fixed time limit. The present European search report has
As all searchable claims could be se did not invite payment of any addition	earched without effort justifying an additional fee, the Search Division anal fee.
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search report has been drawn up to	have been paid within the fixed time limit. The present European in those parts of the European patent application which relate to the highest have been paid, namely claims:
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# LACK OF UNITY OF INVENTION SHEET B

Application Number

EP 99 10 4620

Processor for executing instructions belonging to different formats  2. Claims: 15-21,24  Exexution in parallel of compound instructions
2. Claims: 15-21,24  Exexution in parallel of compound instructions
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### ANNEX TO THE EUROPEAN SEARCH REPORT ON EUROPEAN PATENT APPLICATION NO.

EP 99 10 4620

This annex lists the patent family members relating to the patent documents cited in the above-mentioned European search report. The members are as contained in the European Patent Office EDP file on The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

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